# REPORT 1115

# DESIGN OF TWO-DIMENSIONAL CHANNELS WITH PRESCRIBED VELOCITY DISTRIBUTIONS ALONG THE CHANNEL WALLS <sup>1</sup>

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#### SUMMARY

A general method of design is developed for two-dimensional unbranched channels with prescribed velocities as a function of arc length along the channel walls. The method is developed for both compressible and incompressible, irrotational, non-viscous flow and applies to the design of elbows, diffusers, nozzles, and so forth. Two types of compressible flow are considered: the general type, with the ratio of specific heats  $\gamma$  equal to 1.4, for example, and the linearized type, in which  $\gamma$  is -1.0. Two methods of solution are used: In part I solutions are obtained by relaxation methods; in part II solutions are obtained by a Green's function.

Five numerical examples are given in part I including three elbow designs with the same prescribed velocity as a function of arc length along the channel walls but with incompressible, linearized compressible, and compressible flow. It is concluded that if a nonviscous gas with arbitrary  $\gamma$  (1.4, for example) were to flow through a channel designed for linearized compressible flow ( $\gamma = -1.0$ ), the resulting velocity distribution along the channel walls would be nearly the velocity distribution prescribed for the linearized compressible flow.

One numerical example is presented in part II for an accelerating elbow with linearized compressible flow, and the time required for the solution by a Green's function in part II was considerably less than the time required for the same solution by relaxation methods in part I.

#### INTRODUCTION

There are two general types of theoretical problem in two-dimensional fluid motion: (1) the direct problem, in which the distribution of velocity is determined for a prescribed shape of boundary, and (2) the inverse problem, in which the shape of boundary is determined for a prescribed distribution of velocity along the boundary. The direct problem is an anlaysis problem; the inverse problem is a design problem. This report is concerned with the inverse, or design, problem for two-dimensional, irrotational flow in unbranched channels with prescribed velocities as a function of arc length along the channel walls.

The design of channels with prescribed velocities is important because: (1) Boundary-layer separation losses can be avoided by prescribed velocities that do not decelerate rapidly enough to cause separation, (2) shock losses in compressible flow and cavitation in incompressible flow can be avoided by prescribed velocities that do not exceed certain maximum values dictated by these phenomena, and (3) for compressible flow the desired flow rate can be assured by prescribed velocities that do not result in "choke flow" conditions.

Several methods of channel design have been developed for particular application (refs. 1 and 2, for example). In reference 1 a design method is developed for accelerating elbows in which the velocity increases monotonically along the channel walls. The method is developed for incompressible and linearized ( $\gamma$ =-1.0) compressible flow. The velocity distribution along the channel walls is not arbitrary and the design method applies to elbows only. In reference 2 a design method is developed for straight, symmetrical channels with contracting or expanding walls. The method is developed for incompressible flow and the velocities are prescribed not as a function of arc length along the channel walls but as a function of circle angle in the transformed circle plane. A more general design is suggested in reference 3, but no attempt is made to develop and apply the method.

In the present report a general method of design is developed for two-dimensional, unbranched channels with prescribed velocities as a function of arc length along the channel walls. The method is developed for both compressible and incompressible, irrotational, honviscous flow and applies to the design of elbows, diffusers, nozzles, and so forth. Two types of compressible flow are considered: the general type with arbitrary value of  $\gamma$  (1.4, for example) and the linearized type with  $\gamma$  equal to -1.0. In general, if the prescribed velocity along one channel-wall differs from that along the other, the channel turns so that the downstream flow direction is different from the upstream direction. This change in flow direction cannot be arbitrarily chosen but depends on the prescribed velocity distribution along the walls. Equations are developed for computing this change in flow direction for an arbitrary prescribed velocity distribution with incompressible or linearized compressible flow. Two methods of solution have been developed for the design method and are presented in separate parts of this report. In part I solutions are obtained by relaxation methods (ref. 4). This method of solution results in complete information concerning the distribution of flow conditions throughout the

<sup>1</sup> Superscdes NACA TN 2593, "Design of Two-Dimensional Channels with Prescribed Velocity Distributions Along the Channel Walls. I—Relaxation Solutions" by John D. Stanitz, 1952, and NACA TN 2595, "Design of Two-Dimensional Channels with Prescribed Velocity Distributions Along the Channel Walls. II—Solution by Green's Function" by John D. Stanitz, 1952.

channel and, in addition, can be used to obtain nonlinear solutions for compressible flow with arbitrary values of  $\gamma$ . In part II solutions are obtained by means of a Green's function. This method of solution is limited to incompressible and linearized ( $\gamma = -1.0$ ) compressible flow, but the method is more rapid than relaxation methods, provided information within the channel is not required.

The design method reported herein was developed at the NACA Lewis laboratory during 1950 and is part of a doctoral thesis conducted with the advice of Professor Ascher H. Shapiro of the Massachusetts Institute of Technology.

# PART I

# GENERAL THEORY AND SOLUTION BY RELAXATION METHODS

A general method of design is developed for two-dimensional, unbranched channels with prescribed velocities as functions of arc length along the channel walls. The method is developed for both incompressible and compressible, irrotational, nonviscous flow. Two types of compressible flow are considered: the general type with arbitrary value for the ratio of specific heats  $\gamma$  (1.4, for example), and the linearized type in which  $\gamma$  is equal to -1.0. The solutions in part I of this report are obtained by relaxation methods and give complete information concerning the flow throughout the channel. Five numerical examples are given, including three elbow designs with the same prescribed velocity as a function of arc length along the channel walls but with incompressible, linearized compressible, and compressible flow.

# THEORY OF DESIGN METHOD

The design method is developed for two-dimensional channels with prescribed velocities along the channel walls. The prescribed velocity is arbitrary except that stagnation points cannot be prescribed. This exception limits the design method to unbranched channels.

### PRELIMINARY CONSIDERATIONS

Assumptions.—The fluid is assumed to be nonviscous and either compressible or incompressible. The flow is assumed to be two dimensional and irrotational.

The assumption of two-dimensional, nonviscous, irrotational motion limits the design method in practice to channels with thin (negligible) boundary layers, such as exist near the entrance to the channel or after a rapid acceleration of the flow through a contraction in the channel. Even if the boundary layer is thin, the design method is limited to (and finds its most useful application for) prescribed velocity distributions that, from boundary-layer theory, do not decelerate fast enough to result in separation of the boundary layer, which separation alters the "effective" shape of the channel and completely changes the character of the flow.

In some channels with fully developed turbulent boundary layers, the design method might be expected to yield results that are satisfactory, although approximate, because for this type of flow the rotational motion occurs primarily in regions close to the channel walls. In channel walls with thick or fully developed laminar boundary layers the design method cannot be used, because not only is the rotation of the flow important in most of the channel but, if the channel bends, important secondary flows develop that are not considered by the two-dimensional design method.

Flow field.—The flow field of the two-dimensional channel is considered to lie in the physical xy-plane where x and y are Cartesian coordinates expressed as ratios of a characteristic length equal to the constant channel width downstream at infinity. (All symbols are defined in appendix A.)

At each point in the channel (fig. 1) the velocity vector has a magnitude Q and a direction  $\theta$  where Q is the fluid velocity expressed as the ratio of a characteristic velocity equal to the constant channel velocity downstream at infinity. For convenience, the velocity Q is related to a velocity q by

$$q = Qq_d \tag{1}$$

where q is the velocity expressed as a ratio of the stagnation speed of sound and the subscript d refers to conditions downstream at infinity.

The flow direction  $\theta$  at each point in the channel is measured counterclockwise from the positive x-axis. From figure 1

$$dx = ds \cos \theta$$
 (2a)

$$dy = ds \sin \theta \tag{2b}$$

where ds is a differential distance in the direction of Q, that is, along a streamline.

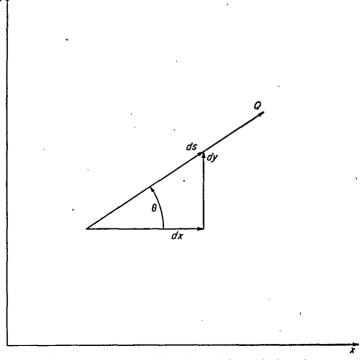


FIGURE 1.—Magnitude and direction of velocity at point in xy-plane.

Stream function and velocity potential.—If the condition of continuity is satisfied, a stream function  $\psi$  can be defined such that

$$d\psi = \rho Q \ dn \tag{3}$$

where  $\rho$  is the fluid density expressed as the ratio of a characteristic density equal to the stagnation density and where dn is a differential distance measured normal to the direction of Q, that is, normal to a streamline. Along a streamline, dn is zero so that from equation (3) the stream function  $\psi$ is constant.

If the condition of irrotational fluid motion is satisfied, a velocity potential  $\varphi$  can be defined such that

$$d\varphi = Q ds$$
 (4)

Normal to a streamline, ds is zero so that from equation (4) the velocity potential  $\varphi$  is constant. Thus lines of constant  $\varphi$  and  $\psi$  are orthogonal in the physical xy-plane.

Outline of method.—Solutions of two-dimensional flow depend on known conditions imposed along the boundaries of the problem. In the inverse problem of channel design, the geometry of the channel walls in the physical xy-plane is unknown. This unknown geometry apparently precludes the possibility of solving the problem in the physical plane and necessitates the use of some new set of coordinates, that is, a transformed plane, in which to solve the problem. These new coordinates must be such that the geometric boundaries along which the velocities are prescribed are known in the transformed plane. It is also desirable, for mathematical simplicity, that the coordinate system in the transformed plane be orthogonal in the physical plane. A set of coordinates that satisfies these requirements is provided by  $\varphi$  and  $\psi$ , which are orthogonal in the physical xy-plane and for which the geometric boundaries are known constant values of  $\psi$  in the transformed  $\varphi\psi$ -plane. The distribution of velocity as a function of  $\varphi$  along these boundaries of constant  $\psi$  is known because, if

$$Q = Q(s)$$

is prescribed, equation (4) integrates to give

$$\varphi = \varphi(s)$$

from which equations,

$$Q = Q(\varphi)$$

The technique of the proposed method of channel design is therefore to obtain a differential equation for the distribution of velocity in the out-plane. The velocity distribution obtained from the solution of this equation is then used to obtain the distribution of flow direction, from which distribution the channel walls in the physical xy-plane are obtained directly. The differential equation for the distribution of velocity in the  $\varphi\psi$ -plane is nonlinear (for compressible flow with  $\gamma$  other than -1.0) and is solved by numerical methods (relaxation methods).

#### DIFFERENTIAL EQUATION FOR DISTRIBUTION OF VELOCITY IN TRANSFORMED ##-PLANE

The differential equation for the distribution of velocity in the transformed  $\varphi\psi$ -plane is obtained from the equations for continuity and irrotational fluid motion expressed in terms of the transformed coordinates  $\varphi$  and  $\psi$ .

Continuity.—The continuity equation expressed in terms of  $\varphi$  and  $\psi$  becomes (appendix B):

$$\frac{1}{\rho} \left( \frac{\partial \log_{e} \rho}{\partial \varphi} + \frac{\partial \log_{e} Q}{\partial \varphi} \right) + \frac{\partial \theta}{\partial \psi} = 0$$
 (5)

Irrotational fluid motion.—The equation for irrotational fluid motion, expressed in terms of  $\varphi$  and  $\psi$ , becomes (appendix B):

$$\rho \frac{\partial \log_{\bullet} Q}{\partial \psi} - \frac{\partial \theta}{\partial \varphi} = 0 \tag{6}$$

Differential equation for distribution of velocity.-The second-order partial differential equation for the distribution of log. Q in the transformed \(\varphi\psi\)-plane is obtained by differentiating equations (5) and (6) with respect to  $\varphi$  and  $\psi$ , respectively, and combining to eliminate  $\frac{\partial^2 \theta}{\partial \omega \partial \omega}$ .

$$\frac{\partial^{2} \log_{e} \rho}{\partial \varphi^{2}} + \frac{\partial^{2} \log_{e} Q}{\partial \varphi^{2}} - \frac{\partial \log_{e} \rho}{\partial \varphi} \left( \frac{\partial \log_{e} \rho}{\partial \varphi} + \frac{\partial \log_{e} Q}{\partial \varphi} \right) + \rho^{2} \frac{\partial \log_{e} Q}{\partial \psi} + \rho^{2} \frac{\partial^{2} \log_{e} Q}{\partial \psi^{2}} = 0 \quad (7)$$

Equation (7), together with a relation between  $\rho$ , Q, and  $q_d$ , determines the distribution of  $\log_{\theta} Q$  in the  $\varphi \psi$ -plane for compressible flow with a given value of  $q_d$  and for arbitrarily prescribed variations in  $\log_e Q$  along the boundaries of constant  $\psi$ .

Density.—The density  $\rho$  is related to the velocity q by (ref. 5, p. 26, for example)

$$\rho = \left(1 - \frac{\gamma - 1}{2} q^2\right)^{\frac{1}{\gamma - 1}} \tag{8a}$$

which, from equation (1), becomes

$$\rho = \left(1 - \frac{\gamma - 1}{2} Q^2 q_d^2\right)^{\frac{1}{\gamma - 1}} \tag{8b}$$

Equation (8b) relates the density  $\rho$  to the velocity Q for a given value of  $q_d$ .

Incompressible flow.—For incompressible flow  $\rho$  is constant and equal to 1.0 so that equation (7) becomes

$$\frac{\partial^2 \log_{\delta} Q}{\partial \varphi^2} + \frac{\partial^2 \log_{\delta} Q}{\partial \psi^2} = 0 \tag{9}$$

Equation (9) determines the distribution of log<sub>e</sub> Q in the φψ-plane for incompressible flow.

# CHANNEL-WALL GEOMETRY

After equation (7) or (9) has been solved to obtain the distribution of log, Q in the transformed  $\varphi\psi$ -plane (for the arbitrary specified variations in  $\log_{\bullet} Q$  with  $\varphi$  along the boundaries of constant  $\psi$ ), the geometry of the channel walls in the physical xy-plane can be determined from the resulting distribution of flow direction  $\theta$ .

Flow direction  $\theta$ .—The distribution of flow direction  $\theta$  along a streamline (constant  $\psi$ ) is obtained from equation (6), which integrates to give

$$\theta = \int_{\psi} \rho \frac{\partial \log_{\bullet} Q}{\partial \psi} \, d\varphi \tag{10a}$$

where the subscript  $\psi$  indicates that the integration is taken along a line of constant  $\psi$  and where the constant of integration is selected to give a known value of  $\theta$  at one value of  $\varphi$  along each streamline. The integrand in equation (10a) is obtained from the distribution of  $\log_{\epsilon} Q$ , which is known from the solution of equation (7) or (9).

The distribution of flow direction  $\theta$  along a velocity-potential line (constant  $\varphi$ ) is obtained from equation (5), which integrates to give

$$\theta = -\int_{\varphi} \frac{1}{\rho} \left( \frac{\partial \log_{\bullet} \rho}{\partial \varphi} + \frac{\partial \log_{\bullet} Q}{\partial \varphi} \right) d\psi \tag{10b}$$

where the subscript  $\varphi$  indicates that the integration is taken along a line of constant  $\varphi$  and where the constant of integration is selected to give a known value of  $\theta$  at one value of  $\psi$  along each velocity-potential line. As for equation (10a), the integrand in equation (10b) is known from the distribution of  $\log_{\theta} Q$  obtained from the solution of equation (7) or (9).

Channel-wall coordinates.—The variation in x along a line of constant  $\psi$  in the  $\varphi\psi$ -plane is given by

$$\frac{\partial x}{\partial \varphi} = \left(\frac{dx}{ds} \frac{ds}{d\varphi}\right)_{\psi}$$

which, combined with equations (2a) and (4), integrates to give

$$x = \int_{\mathcal{L}} \frac{\cos \theta}{Q} \, d\varphi \tag{11a}$$

Likewise,

$$x = -\int_{\Gamma} \frac{\sin \theta}{\rho Q} d\psi \tag{11b}$$

$$y = \int_{\phi} \frac{\sin \theta}{Q} d\varphi \tag{11c}$$

$$y = \int_{\sigma} \frac{\cos \theta}{\rho \, Q} \, d\psi \tag{11d}$$

where the constants of integration are selected to give known values of x or y at one value of  $\varphi$  along each streamline or at one value of  $\psi$  along each velocity-potential line. Equations (11a) to (11d) determine the distribution of x and y in the transformed  $\varphi\psi$ -plane or, which is the same thing, the shape of the streamlines and velocity-potential lines in the physical xy-plane. In particular, equations (11a) and (11c) when integrated along the boundaries of constant  $\psi$  in the  $\varphi\psi$ -plane determine the shape of the channel walls.

Turning angle.—In general, if the prescribed velocity distribution along one channel wall differs from the distribution along the other wall, the channel deflects an amount  $\Delta\theta$ , which is the difference in flow direction far downstream and far upstream of the region in which the prescribed velocity

distribution varies. In part II it is shown that for incompressible flow the turning angle  $\Delta\theta$  is given by

$$\Delta\theta = \theta_d - \theta_u$$

$$= -\int_{-\infty}^{\infty} \varphi \left[ \left( \frac{\partial \log_{\epsilon} Q}{\partial \varphi} \right)_{1,0} - \left( \frac{\partial \log_{\epsilon} Q}{\partial \varphi} \right)_{0} \right] d\varphi \qquad (12)$$

where the subscript u refers to conditions upstream at infinity and where the subscripts 0 and 1.0 refer to the channe boundaries along which  $\psi$  equals 0 and 1.0, respectively. A similar equation will be given later for the case of linearized compressible flow.

#### LINEARIZED COMPRESSIBLE FLOW

The nonlinear differential equation (7) for the distribution of velocity in the  $\varphi\psi$ -plane with compressible flow becomes linear and is considerably simplified if a linear variation in pressure with specific volume (1/ $\rho$ ) is assumed. This linear relation between pressure and specific volume was first suggested by Chaplygin (ref. 6) in order to linearize the differential equations for two-dimensional compressible flow in the hodograph plane.

Density.—If a linear variation in pressure with specific volume is assumed, the density  $\rho^*$  is related to the velocity  $q^*$  by (appendix C)

$$\rho^* = (1 + q^{*2})^{-1/2} \tag{13}$$

where

$$\rho^* = k_1 \rho \tag{13a}$$

and

$$q^* = k_2 q \tag{13b}$$

where the constants  $k_1$  and  $k_2$  have been determined so that values of  $\rho$  given by equation (13) equal the values of  $\rho$  given by equation (8a) for any two selected values of  $\rho$  (designated by  $\rho$  and  $\rho$ ). Thus,

$$c_1 = \frac{1}{\rho_a} \sqrt{\frac{1 - \left(\frac{\rho_a q_a}{\rho_b q_b}\right)^2}{1 - \left(\frac{q_a}{q_b}\right)^2}} \tag{14a}$$

and

$$k_2 = \frac{1}{q_b} \sqrt{\frac{\left(\frac{\rho_a}{\rho_b}\right)^2 - 1}{1 - \left(\frac{\rho_a q_a}{\rho_b q_b}\right)^2}} \tag{14b}$$

where  $\rho_a$  and  $\rho_b$  are determined by equation (8a) for the selected values of  $q_a$  and  $q_b$ , respectively. A discussion of the selection of  $q_a$  and  $q_b$  is given in appendix C. It will be noted that, if  $\gamma$  is equal to -1.0, equation (8a) has the same form as equation (13).

Stream function and velocity potential.—For the case of linearized compressible flow it is convenient to define the stream function  $\psi^*$  and the velocity potential  $\varphi^*$  by

$$d\psi^* = \rho^* q^* \ dn \tag{15}$$

and

$$d\varphi^* = q^* ds \tag{16}$$

Continuity.—The continuity equation expressed in terms of  $\varphi^*$  and  $\psi^*$  becomes (appendix D)

$$\frac{\partial \log_{\theta} u}{\partial u^{*}} + \frac{\partial \theta}{\partial u^{*}} = 0 (17)$$

where

$$u = \frac{q^*}{1 + \sqrt{1 + q^{*2}}} \tag{18}$$

or, conversely,

$$q^* = \frac{2u}{1 - u^2} \tag{19}$$

Irrotational fluid motion.—The equation for irrotational fluid motion, expressed in terms of  $\varphi^*$  and  $\psi^*$ , becomes (appendix D)

$$\frac{\partial \log_{\theta} u}{\partial u^*} - \frac{\partial \theta}{\partial \omega^*} = 0 \tag{20}$$

Differential equation for distribution of  $\log_e u$ .—The partial differential equation for the distribution of  $\log_e u$  in the  $\varphi^*\psi^*$ -plane is obtained by differentiating equations (17) and (20) with respect to  $\varphi^*$  and  $\psi^*$ , respectively, and combining to eliminate  $\frac{\partial^2 \theta}{\partial \varphi^* \partial \psi^*}$ . Thus

$$\frac{\partial^2 \log_{\delta} u}{\partial \omega^{*2}} + \frac{\partial^2 \log_{\delta} u}{\partial \psi^{*2}} = 0 \tag{21}$$

Equation (21) determines the distribution of  $\log_{\bullet} u$  in the  $\varphi^*\psi^*$ -plane for linearized compressible flow with a given value of  $q_{\bullet}$  and for arbitrarily prescribed variations in  $\log_{\bullet} Q$ , related to  $\log_{\bullet} u$  by equations (1), (13b), and (18), along the boundaries of constant  $\psi^*$ . Equation (21) is linear and is, like equation (9) for the case of incompressible flow, the equation of Laplace. Thus an incompressible flow solution for the distribution of  $\log_{\bullet} Q$  in the  $\varphi\psi$ -plane is also a linearized compressible flow solution for the distribution of  $\log_{\bullet} u$  in the  $\varphi^*\psi^*$ -plane. The transformation from the  $\varphi\psi$ -plane is different, however, from the transformation from the  $\varphi^*\psi^*$ -plane so that different channel shapes result in the xy-plane.

Flow direction  $\theta$ .—The distribution of flow direction  $\theta$  along a streamline (constant  $\psi^*$ ) is obtained from equation (20), which integrates to give

$$\theta = \int_{u^*} \frac{\partial \log_* u}{\partial \psi^*} \, d\varphi^* \tag{22a}$$

Likewise, the distribution of flow direction  $\theta$  along a velocity-potential line (constant  $\varphi^*$ ) is obtained from equation (17), which integrates to give

$$\theta = -\int_{\varphi^*} \frac{\partial \log_{\epsilon} u}{\partial \varphi^*} \, d\psi^* \tag{22b}$$

Equations (22a) and (22b) for linearized compressible flow correspond to, and are used in the same manner as, equations (10a) and (10b) for the usual type of compressible or incompressible flow.

Channel-wall coordinates.—The variation in x along a line of constant  $\psi^*$  in the  $\varphi^*\psi^*$ -plane is given by

$$\frac{\partial x}{\partial \varphi^*} = \left(\frac{dx}{ds} \frac{ds}{d\varphi^*}\right)_{\varphi^*} .$$

which combined with equations (2a) and (16) integrates to give

$$x = \int_{\psi^*} \frac{\cos \theta}{q^*} \, d\varphi^* \tag{23a}$$

Likewise,

$$x = -\int_{\tau^*} \frac{\sin \theta}{\rho^* q^*} d\psi^* \tag{23b}$$

$$y = \int_{u^*} \frac{\sin \theta}{q^*} \, d\varphi^* \tag{23c}$$

$$y = \int_{\bullet^*} \frac{\cos \theta}{\rho^* q^*} d\psi^* \tag{23d}$$

Equations (23a) to (23d) determine the distribution of x and y in the transformed  $\varphi^*\psi^*$ -plane or, which is the same thing, the shape of the streamline and velocity-potential lines in the physical xy-plane. In particular, equations (23a) and (23c), when integrated along the boundaries of constant  $\psi^*$  in the  $\varphi^*\psi^*$ -plane, determine the shape of the channel walls. Equations (23a) to (23d) for linearized compressible flow correspond to, and are used in the same manner as, equations (11a) to (11d) for the usual type of compressible or incompressible flow.

Turning angle.—In part II it is shown that for linearized compressible flow the turning angle, or difference in flow direction far downstream and far upstream of the region in which the prescribed velocity distribution varies along the channel walls, is given by

$$\Delta \theta = \frac{-1}{\Delta \psi^*} \int_{-\infty}^{\infty} \varphi^* \left[ \left( \frac{\partial \log_{\bullet} u}{\partial \varphi^*} \right)_{\Delta \psi^*} - \left( \frac{\partial \log_{\bullet} u}{\partial \varphi^*} \right)_{0} \right] d\varphi^* \quad (24)$$

where  $\Delta \psi^*$  is the value of  $\psi^*$  along the left boundary (channel wall) when faced in the direction of flow if the value of  $\psi^*$  along the right boundary is zero, and where the subscript  $\Delta \psi^*$  refers to the boundary along which  $\psi^*$  is equal to  $\Delta \psi^*$ .

# NUMERICAL PROCEDURE

The channel design method in part I of this report was developed for three types of fluid flow: (1) compressible, (2) incompressible, and (3) linearized compressible. Although the numerical procedures of the design method are similar for each type of fluid, the procedures differ in detail and are therefore considered separately in this section.

# COMPRESSIBLE FLOW

The numerical procedure for channel design with compressible flow ( $\gamma=1.4$ , for example) is as follows:

(1) The velocity is specified as a function of arc length along that portion of the channel walls over which the velocity varies

$$q=q(s)$$

or  $q_d$  is specified and

$$Q = Q(s) \tag{25}$$

where s is arbitrarily equal to zero at that point along one channel wall where the velocity first begins to vary.

(2) The channel-wall boundaries of the flow field in the transformed  $\varphi\psi$ -plane are straight, parallel lines of constant  $\psi$  extending indefinitely far upstream and downstream between  $\varphi$  equals  $\pm \infty$ , where  $\varphi$  is arbitrarily equal to zero at that point on the channel wall at which  $\varepsilon$  is equal to zero. The value of  $\psi$  along the right channel wall when faced in the direction of flow (direction of positive  $\varphi$ ) is arbitrarily set equal to zero in which case the value of  $\psi$  along the left channel wall ( $\Delta\psi$ ) is obtained by integrating equation (3) across the channel at a position far downstream where flow conditions are uniform

$$\Delta \psi = \rho_d \tag{26}$$

(3) The distribution of  $\log_{\epsilon} Q$  as a function of  $\varphi$  along the boundaries in the  $\varphi\psi$ -plane is obtained by integrating equation (4) between limits so that

$$\varphi = \int_0^s Q \, ds = \varphi(s) \tag{27}$$

which together with equation (25) gives the distribution of  $\log_e Q$  along the boundaries in the  $\varphi \psi$ -plane

$$\log_{\bullet} Q = f(\varphi) \tag{28}$$

The integration indicated by equation (27) is carried out numerically for arbitrary distributions of Q as a function of s.

- (4) If the velocities prescribed along one channel wall differ from those along the other wall, the channel will, in general, turn the flow. This turning angle cannot be determined exactly for compressible flow until the channel design is completed. However, it will be shown that this turning angle is only slightly greater than that resulting for linearized compressible flow with the same prescribed velocity and with a suitable selection for  $q_a$  and  $q_b$  in equations (14a) and (14b). This latter turning angle for linearized compressible flow is given by equation (24), which can be integrated numerically for the arbitrary distribution of  $\log_b u = f(\varphi)$  corresponding to equation (28).
- (5) In order to solve equation (7) for the distribution of  $\log_{\bullet} Q$  in the  $\varphi \psi$ -plane, it is convenient to eliminate the density terms from equation (7) by means of equation (8b). Thus, equation (7) becomes

$$A\frac{\partial^{2} \log_{\epsilon} q}{\partial \varphi^{2}} + B\frac{\partial^{2} \log_{\epsilon} q}{\partial \psi^{2}} + 4C\left(\frac{\partial \log_{\epsilon} q}{\partial \varphi}\right)^{2} + 4D\left(\frac{\partial \log_{\epsilon} q}{\partial \psi}\right)^{2} = 0$$
(29)

where

$$A = \frac{1 - \frac{\gamma + 1}{2} q^2}{\left(1 - \frac{\gamma - 1}{2} q^2\right)^{\frac{\gamma + 1}{\gamma - 1}}}$$

$$B = 1.0$$

$$4C = \frac{-q^2 \left(1 + \frac{\gamma + 1}{2} q^2\right)}{\left(1 - \frac{\gamma - 1}{2} q^2\right)^{\frac{2\gamma}{\gamma - 1}}}$$

and

$$4D = \frac{-q^2}{1 - \frac{\gamma - 1}{2}q^2}$$

Equation (29) is nonlinear, and it can be solved by relaxation methods (refs. 4 and 7, for example). A grid of equally spaced points, at each of which the value of log. Q is to be determined, is placed in the flow field between the channelwall boundaries. The grid is extended upstream and downstream sufficiently far so that constant values of log. Q are obtained across the channel by the relaxation methods. In the numerical examples to be presented six or eight grid spaces were used across the channel. In example III the number of grid spaces was reduced from eight to four with negligible effect on the resulting channel design. The values of loge Q at each grid point were relaxed to five significant figures. If the same velocity distribution is prescribed along both walls, the channel is symmetrical so that the velocity distribution in only one half of the channel need be determined by relaxation methods.

- (6) After log. Q has been determined at each grid point in the  $\varphi \psi$ -plane, the distribution of  $\theta$  is determined by equations (10a) and (10b), which are integrated numerically. The constants of integration in equations (10a) and (10b) are determined to give a specified value of  $\theta$  at one point in the channel (far upstream, for example). The integrands in equations (10a) and (10b) are determined by numerical methods (tables I to VII, ref. 4, for example) from the known values of  $\rho$  and  $\log_e Q$  at each of the grid points. If it is desired to know the flow direction along the channel-walls only, equation (10a) can be solved along the channel-wall boundaries  $\psi=0$  and  $\psi=\Delta\psi$  only. If it is desired to know  $\theta$  everywhere in the channel, the recommended procedure is to determine the variation in  $\theta$  along the mean streamline  $(\psi = (\Delta \psi)/2)$  by equation (10a) and to determine the variation in  $\theta$  along each velocity-potential line from the previously determined values on the mean streamline by equation (10b).
- (7) After the distributions of  $\log_{\theta} Q$  and  $\theta$  are known in the φψ-plane, the shapes of the streamlines and the velocitypotential lines in the physical xy-plane or, which is the same thing, the distributions of x and y in the transformed  $\varphi \psi$ plane are determined by the numerical integration of equations (11a) to (11d). The constants of integration in these equations are determined so that specified values of x and y occur at one point in the flow field. The recommended procedure is to determine the variation in x and y along the mean streamline by equations (11a) and (11c) and to determine the variation in x and y along each velocity-potential line for the previously determined values on the mean streamline by equations (11b) and (11d). If it is desired to know the x and y coordinates for the channel walls only, equations (11a) and (11c) can be solved along the channelwall boundaries  $\psi = 0$  and  $\psi = \Delta \psi$  only.

#### INCOMPRESSIBLE FLOW

The numerical procedure for channel design with incompressible flow  $(\rho=1)$  is similar to that just outlined for compressible flow, but with the following differences:

- (1) The velocity is specified as a function of arc length by equation (25) alone.
- (2) The value of  $\psi$  along the left channel wall  $(\Delta \psi)$  is equal to 1.0 instead of the value given by equation (26).
- (3) The distribution of  $\log_{\epsilon} Q$  as a function of  $\varphi$  along the channel-wall boundaries in the  $\varphi\psi$ -plane is the same as that obtained from equations (25) and (27) and given by equation (28).
- (4) The turning angle  $\Delta\theta$  of the channel is given by equation (12).
- (5) The distribution of  $\log_{\bullet} Q$  in the  $\varphi \psi$ -plane is obtained from the solution of equation (9) by relaxation methods.
- (6) After log<sub>e</sub> Q has been determined at each grid point between the channel-wall boundaries in the  $\varphi \psi$ -plane, the distribution of  $\theta$  is determined by equations (10a) and (10b) as indicated previously for compressible flow, but with  $\rho$ equal to unity.
- (7) After the distributions of  $\log_{\theta} Q$  and  $\theta$  are known in the  $\varphi\psi$ -plane, the shapes of the streamlines and velocity-potential lines in the physical xy-plane are determined by equations (11a) to (11d) as indicated previously for compressible flow, but with  $\rho$  equal to unity.

#### LINEARIZED COMPRESSIBLE FLOW

The numerical procedure for channel design with linearized compressible flow ( $\gamma = -1.0$ ) is similar to that previously outlined for compressible flow, but with the following differences:

(1) The velocity q is specified as a function of arc length along the channel walls by q(s) or by  $q_d$  and equation (25). For each prescribed velocity, there are an infinite number of linearized compressible flow solutions depending on the selected values of  $q_a$  and  $q_b$  in equations (14a) and (14b). However, for values of  $q_a$  and  $q_b$  within the range of q prescribed along the channel walls (and therefore everywhere in the channel), the solutions, that is, channel shapes, probably differ only in small detail. The best solution is that most nearly like the nonlinear compressible solution with arbitrary value of  $\gamma$  (1.4, for example). In the numerical examples of this report it is shown that, if  $q_a$  and  $q_b$  are equal to the maximum and minimum values of q, a good solution results, at least if the ratio of these prescribed velocities is not too large (2:1 in the numerical examples). On the other hand, if continuity is to be satisfied for a gas with the correct value of  $\gamma$ (1.4, for example) upstream and downstream of the region of the channel in which the prescribed velocities vary, then  $q_a$  and  $q_b$  must equal  $q_u$  and  $q_d$ .

After  $q_a$  and  $q_b$  have been selected, the velocity distribution q(s) is expressed as  $q^*(s)$  by equation (13b) where  $k_2$  is given by equation (14b) so that

$$q^* = q^*(s) \tag{30}$$

The velocity  $q^*$  is then expressed as u by equation (18) so that

$$u = u(s) \tag{31}$$

In the particular case where the selected value of  $q_a$  is equal to  $q_b$ , the value of  $k_2$  is given by equation (C4b) in appendix C, where the significance of this particular case is also discussed.

(2) The solution is obtained in the transformed  $\varphi^*\psi^*$ plane where  $\varphi^*$  and  $\psi^*$  are defined by equations (16) and (15), respectively. If the value of  $\psi^*$  along the right channel wall when faced in the direction of  $q^*$  is zero, the value of  $\psi^*$  along the left wall  $(\Delta \psi^*)$  is obtained by integrating equation (15) across the channel at a position far downstream where flow conditions are uniform

$$\Delta \psi^* = \rho_d^* q_d^* \tag{32}$$

(3) The distribution of  $\log_{\bullet} u$  as a function of  $\varphi^*$  along the channel-wall boundaries in the  $\varphi^*\psi^*$ -plane is obtained by integrating equation (16) between limits similar to those discussed previously for compressible flow so that

$$\varphi^* = \int_0^s q^* \ ds = \varphi^*(s) \tag{33}$$

which together with equation (31) determines the distribution of log, u along the channel-wall boundaries in the  $\varphi^*\psi^*$ plane

$$\log_{\epsilon} u = f(\varphi^*) \tag{34}$$

- (4) The turning angle  $\Delta\theta$  of the channel is given by equation (24).
- (5) The distribution of  $\log_e u$  in the  $\varphi^*\psi^*$ -plane is obtained from the solution of equation (21) by relaxation methods.
- (6) After log, u has been determined at each grid point between the channel-wall boundaries in the  $\varphi^*\psi^*$ -plane, the distribution of  $\theta$  is determined by equations (22a) and (22b) in a manner similar to that outlined previously for compressible flow.
- (7) After the distributions of  $\log_{\bullet} u$  and  $\theta$  are known in the  $\varphi^*\psi^*$ -plane, the shapes of the streamlines and the velocitypotential lines in the physical xy-plane are determined by equations (23a) to (23d) in a manner similar to that outlined previously for compressible flow. The velocities  $q^*$  in equations (23) are obtained from the known values of u, and the densities  $\rho^*$  are given by equation (13).

### NUMERICAL EXAMPLES

The channel design method has been applied in part I to the five examples listed below:

Examples	Type of channel	Type of flow
I	Reducing section	Incompressible
п	Converging section	Incompressible
ш	Elbow	Incompressible
, IA	Elbow	Linearized compressible
v	Elbow	Compressible (γ=1.4)

# EXAMPLE 1

The first numerical example is the design of a reducing section in a straight channel such that the upstream velocity is half the downstream velocity. The solution is for incompressible flow.

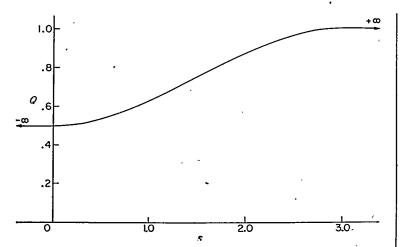


FIGURE 2.—Prescribed velocity distribution as function of arc length along channel wall for examples I, III, IV, and V. Equation (35).

Prescribed velocity distribution.—The prescribed velocity as a function of arc length s along both channel walls is given by

$$Q=0.5 (s \le 0)$$

$$Q=\frac{1}{2} + \frac{s^2}{6} - \frac{s^3}{27} (0 \le s \le 3.0)$$

$$Q=1.0 (s \le 3.0)$$
(35)

The prescribed velocity given by equation (35) is plotted in figure 2.

Equation (35) together with equation (27) results in

$$\varphi = 0.5s \qquad (s \le 0)$$

$$\varphi = \frac{s}{2} + \frac{s^3}{18} - \frac{s^4}{108} \qquad (0 \le s \le 3.0)$$

$$\varphi = -0.75 + s \qquad (s < 3.0)$$
(36)

From equations (35) and (36),  $\log_{\bullet} Q$  is a known function of  $\varphi$ , which function is plotted in figure 3.

Results.—The results of example I are presented in figures 4 to 7.

In figure 4, lines of constant velocity Q and flow direction  $\theta$  are plotted in the transformed  $\varphi\psi$ -plane. The flow direction  $\theta$  is constant and equal to zero along the mean streamline  $(\psi=0.5)$ , indicating that the center line of the channel is straight. The maximum absolute values of  $\theta$  occur along the channel walls. The solution is symmetrical about the mean-streamline. The lines of constant Q and  $\theta$  are orthogonal.

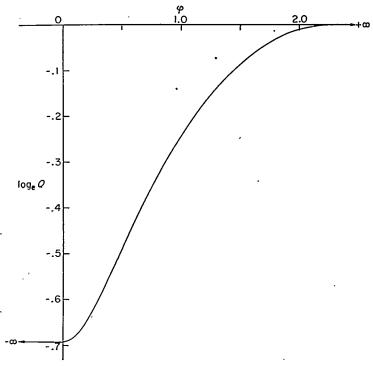


FIGURE 3.—Prescribed distribution of log. Q as function of \(\phi\) along channel walls for example I.

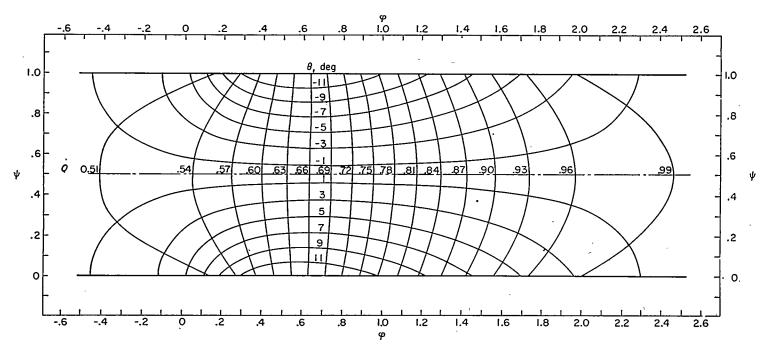


FIGURE 4.—Lines of constant velocity Q and flow direction θ in transformed φψ-plane for example I. Incompressible flow; prescribed velocity given in figure 2.

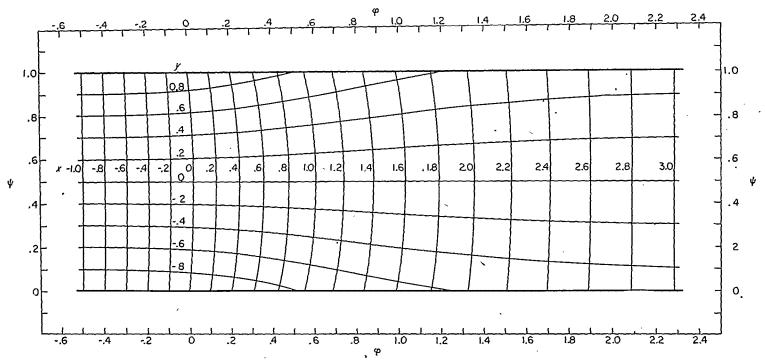


Figure 5.—Lines of constant x and y coordinates in transformed  $\phi \psi$ -plane for example I. Incompressible flow; prescribed velocity given in figure 2.

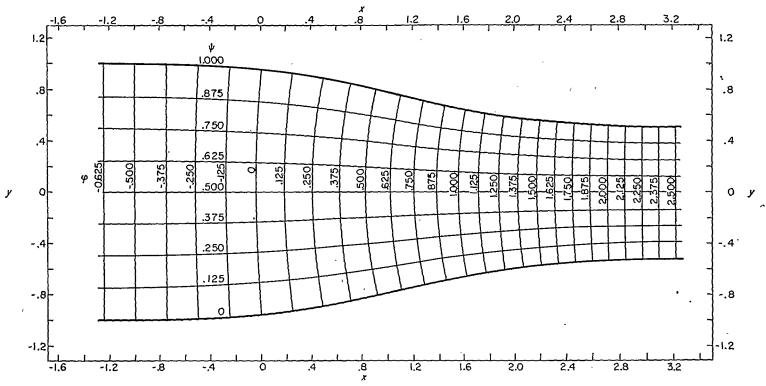


FIGURE 6.—Streamlines and velocity-potential lines on physical xy-plane for example I. Incompressible flow; prescribed velocity given in figure 2.

In figure 5, lines of constant x and y are plotted on the transformed  $\varphi\psi$ -plane. Along the mean streamline ( $\psi$ =0.5) the value of y is constant and equal to zero indicating, as before, that the center line of the channel is straight. The lines of constant x and y are orthogonal, and the system of curves forms a square network. The solution is symmetrical.

In figure 6, lines of constant  $\varphi$  and  $\psi$  (velocity potential and streamlines, respectively) are plotted in the physical xyplane. The shape of the channel walls is that required to result in the prescribed velocity distribution given by equation (35) and plotted in figure 2. The downstream channel width is 1.0 by definition. The upstream channel width is 2.0 in order that the upstream velocity be half the down-

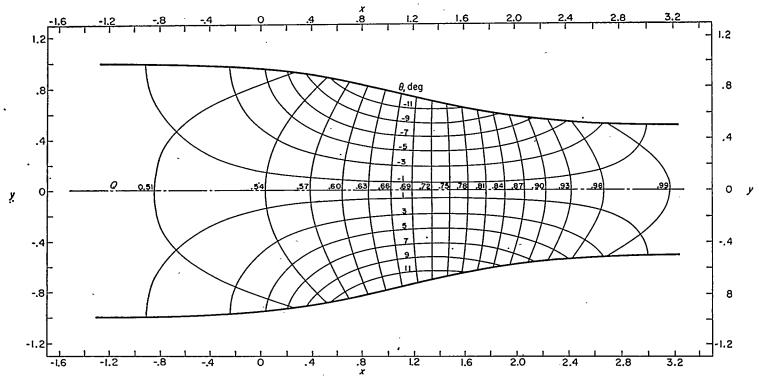


FIGURE 7.—Lines of constant velocity Q and flow direction  $\theta$  in physical xy-plane for example I. Incompressible flow; prescribed velocity given in figure 2.

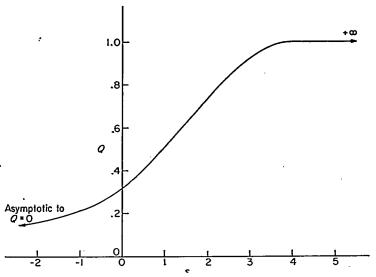


FIGURE 8.—Prescribed volocity distribution as function of arc length along channel wall for example II. Equation (38).

stream velocity. As usual, the streamlines and velocity potential lines are orthogonal and, with equal increments of  $\varphi$  and  $\psi$ , form a square network for incompressible flow.

In figure 7, lines of constant Q and  $\theta$  are plotted in the physical xy-plane. The lines of constant Q and  $\theta$  are orthogonal.

#### EXAMPLE II

The second numerical example is the design of a converging section that funnels the fluid from an infinite expanse into a straight channel of unit width. Far upstream the channel walls are straight and converge at a 90° angle. The solution is for incompressible flow.

Prescribed velocity distribution.—The prescribed velocity as a function of arc length s along both channel walls is given by

$$Q = \frac{-2}{\pi (s-2)}$$

$$Q = \frac{1}{\pi} + \frac{1}{2\pi} s - \frac{1}{8} \left( \frac{7}{2\pi} - \frac{3}{2} \right) s^2 + \frac{1}{32} \left( \frac{2}{\pi} - 1 \right) s^3$$

$$Q = 1.0$$

$$(s \le 0)$$

$$(0 \le s \le 4)$$

$$(s \ge 4)$$

The prescribed velocity given by equation (37) is plotted in figure 8.

Equation (37) together with equation (27) results in

$$\varphi = \frac{-2}{\pi} \log_{\epsilon} \left( 1 - \frac{s}{2} \right) \qquad (s \le 0)$$

$$\varphi = \frac{1}{\pi} s + \frac{1}{2\pi} \frac{s^{2}}{2} - \frac{1}{8} \left( \frac{7}{2\pi} - \frac{3}{2} \right) \frac{s^{3}}{3} + \frac{1}{32} \left( \frac{2}{\pi} - 1 \right) \frac{s^{4}}{4} \qquad (0 \le s \le 4)$$

$$\varphi = \frac{8}{3\pi} - 2 + s \qquad (s \ge 4)$$

From equations (37) and (38),  $\log_{\bullet} Q$  is a known function of  $\varphi$ , which function is plotted in figure 9.

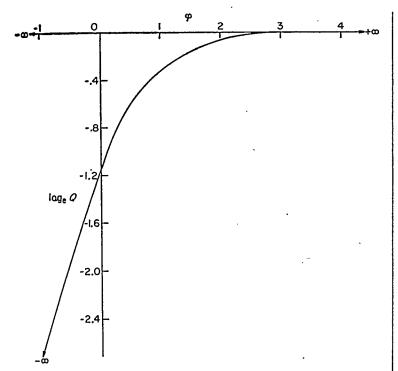


FIGURE 9.—Prescribed distribution of log. Q as function of \varphi along channel walls for example II.

Results.—The results of example  $\Pi$  are presented in figures 10 to 12.

In figure 10, lines of constant velocity Q and flow direction  $\theta$  are plotted in the transformed  $\varphi\psi$ -plane. The flow direction  $\theta$  is constant and equal to zero along the mean streamline ( $\psi$ =0.5), indicating that the center line of the channel is straight. The solution is symmetrical about the mean streamline. As for example I, the lines of constant Q and  $\theta$  are orthogonal.

In figure 11, lines of constant  $\varphi$  and  $\psi$  are plotted in the physical xy-plane. The shape of the channel walls is that

required to result in the prescribed velocity distribution given by equation (37) and plotted in figure 8. As usual, the streamlines and velocity-potential lines are orthogonal and, for incompressible flow with equal increments of  $\varphi$  and  $\psi$ , form a square network.

In figure 12, lines of constant Q and  $\theta$  are plotted in the physical xy-plane. The lines of constant Q and  $\theta$  are orthogonal.

#### EXAMPLE III

The third numerical example is the design of an elbow for which the upstream velocity is half the downstream velocity. The prescribed velocities are such that no deceleration occurs anywhere along the channel walls. The solution is for incompressible flow.

Prescribed velocity distribution.—Along both walls upstream of the elbow the velocity Q is equal to 0.5, and along both walls downstream of the elbow Q is equal to 1.0. The transition from Q equals 0.5 to 1.0 along both walls of the elbow will be the prescribed velocity distribution as a function of arc length given by equation (35) for example I and plotted in figure 2. In terms of  $\log_{\epsilon} Q$  as a function of  $\varphi$ , this prescribed velocity distribution is given by equation (36) and is plotted in figure 3. Although this velocity distribution is the same for both walls, the distribution on the outer wall (wall with larger radii of curvature) is shifted in the positive  $\varphi$  direction an amount equal to 2.25 relative to the distribution on the inner wall. Thus, a velocity difference exists on the two walls at equal values of  $\varphi$ , as shown in figure 13. The greater this difference in velocity and the greater the range in  $\varphi$  over which velocity differences exist, the greater is the elbow turning angle. For the prescribed velocity distribution given in figure 13, the elbow turning angle given by equation (12) was 89.37° compared with a value of 89.36° obtained from the relaxation solution.

Results.—The results of example  $\Pi I$  are presented in figures 14 to 16 and in tables I and  $\Pi$ . (The numerical

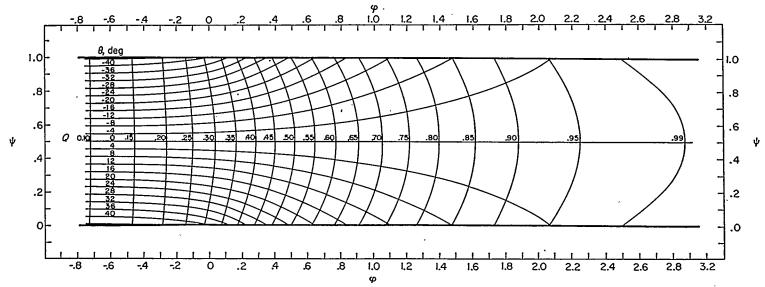


FIGURE 10.—Lines of constant velocity Q and flow direction  $\theta$  in transformed  $\varphi\psi$ -plane for example II. Incompressible flow; prescribed velocity given in figure 8.

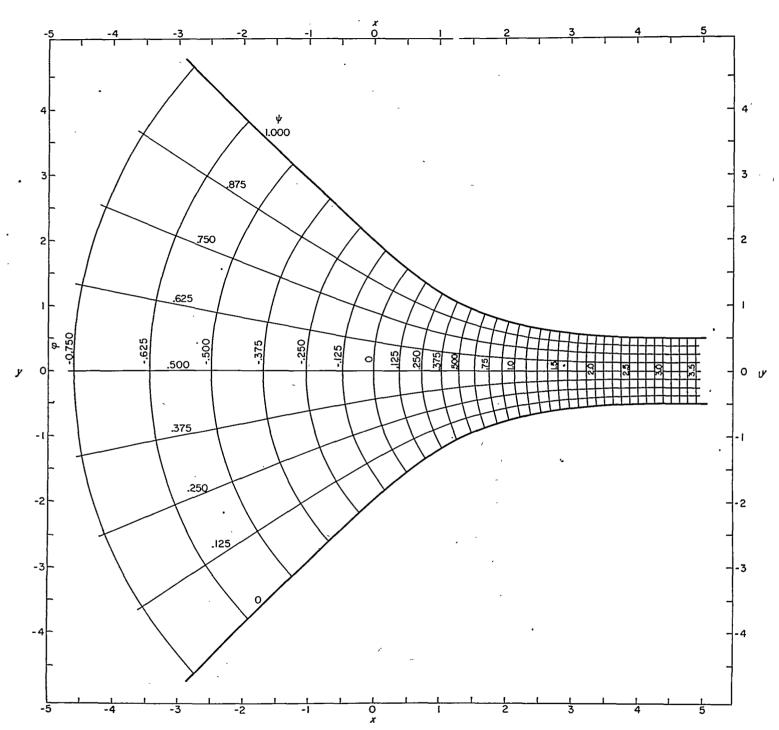


FIGURE 11.—Streamlines and velocity-potential lines in physical xy-plane for example II. Incompressible flow; prescribed velocity given in figure 8.

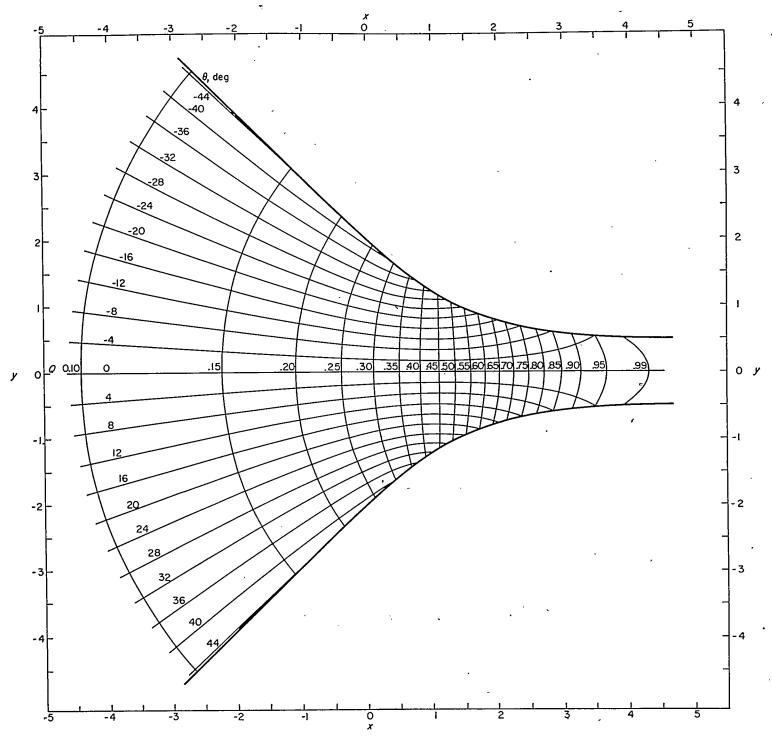


FIGURE 12.—Lines of constant velocity Q and flow direction  $\theta$  in physical xy-plane for example  $\Pi$ . Incompressible flow; prescribed velocity given in figure 8.

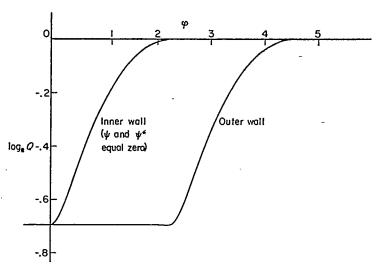


FIGURE 13.—Prescribed distribution of  $\log_{\bullet}Q$  as function of  $\varphi$  along channel walls for examples III. IV. and V.

results for examples III, IV, and V are tabulated in tables I to VI to enable a detailed comparison of the three elbow designs with the same prescribed velocity Q distribution as a function of arc length but with incompressible (example III), linearized compressible (example IV), and compressible (example V) flow.)

In figure 14, lines of constant Q and  $\theta$  are plotted in the  $\varphi\psi$ -plane. The flow direction  $\theta$  varies along the mean streamline ( $\psi$ =0.5), indicating that the channel is curved. The solution is unsymmetrical. As for examples I and II, the lines of constant Q and  $\theta$  are orthogonal.

In figure 15, lines of constant  $\varphi$  and  $\psi$  are plotted in the physical xy-plane. The shape of the channel walls is that required to result in the prescribed velocity distribution given by equations (35) and (36) and plotted in figures 2 and 13. The upstream channel width is twice the downstream width in order that the upstream velocity be half the downstream velocity. It is interesting to note that, before curving in the direction of the elbow turning angle, the inner wall first curves in the opposite direction. This behavior of the inner-wall geometry is necessary in order to

maintain the prescribed constant velocity along the outer wall where the velocity would otherwise decelerate because of the necessary curvature in the direction of elbow turning. This feature of the elbow geometry will also be noted in examples IV and V. As usual, the streamlines and velocity-potential lines are orthogonal and, for equal increments of  $\varphi$  and  $\psi$ , form a square network.

In figure 16, lines of constant Q and  $\theta$  are plotted in the physical xy-plane. The lines of constant Q and  $\theta$  are orthogonal.

#### EXAMPLE IV

The fourth numerical example is the design of an elbow with the same prescribed velocity Q, as a function of arc length, used in example III but for linearized compressible flow  $(\gamma = -1.0)$ .

Prescribed velocity distribution.—The prescribed velocity distribution Q is the same as that for example III and with  $q_d$  equal to 0.80176. The variation in Q with s along one channel wall is plotted in figure 2. The values of  $q_a$  and  $q_b$  in equations (14a) and (14b) are equal to  $q_a$  and  $q_d$ , or 0.40088 and 0.80176, respectively. For these values of  $q_a$  and  $q_b$  and for the prescribed velocity distribution with linearized compressible flow, the elbow turning angle given by equation (24) was 104.08° compared with a value of 104.07° obtained from the relaxation solution and a value of 89.36° obtained for incompressible flow (example III).

Results.—The results of example IV are presented in figures 17 to 19 and in tables III and IV.

In figure 17, lines of constant q and  $\theta$  are plotted in the transformed  $\varphi^*\psi^*$ -plane. The solution is unsymmetrical and the lines of constant q and  $\theta$  are orthogonal.

In figure 18, lines of constant  $\varphi^*/\Delta\psi^*$  and  $\psi^*/\Delta\psi^*$  are plotted in the physical xy-plane (where the constant  $\Delta\psi^*$  is given by equation (32) and is equal to 0.73782 for  $q_d$  equal to 0.80176). The shape of the channel walls is that required to result in the prescribed velocity distribution used in example III but with linearized compressible flow and for  $q_d$  equal to 0.80176. From continuity considerations the upstream channel width is 1.5385 times the downstream width. As in example III, the inner wall of the elbow first

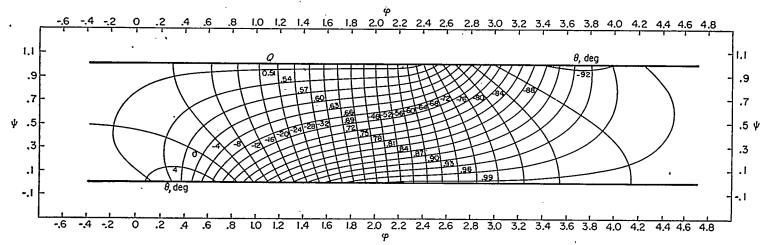


FIGURE 14.—Lines of constant velocity Q and flow direction \(\theta\) in transformed \(\phi\)!—plane for example III. Incompressible flow; prescribed velocity given in figures 2 and 13.

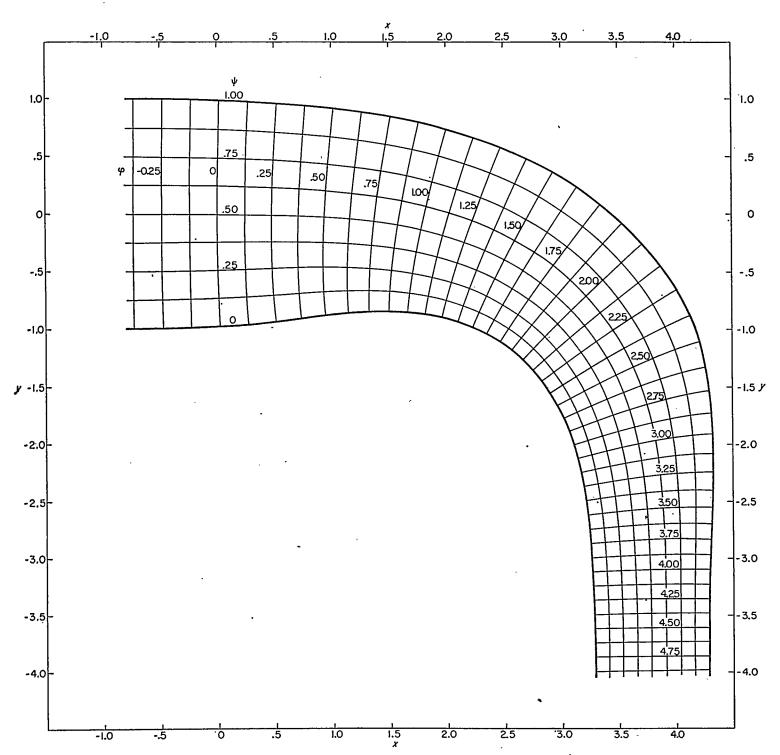


Figure 15.—Streamlines and velocity-potential lines in physical xy-plane for example III. Incompressible flow; prescribed velocity given in figures 2 and 13.

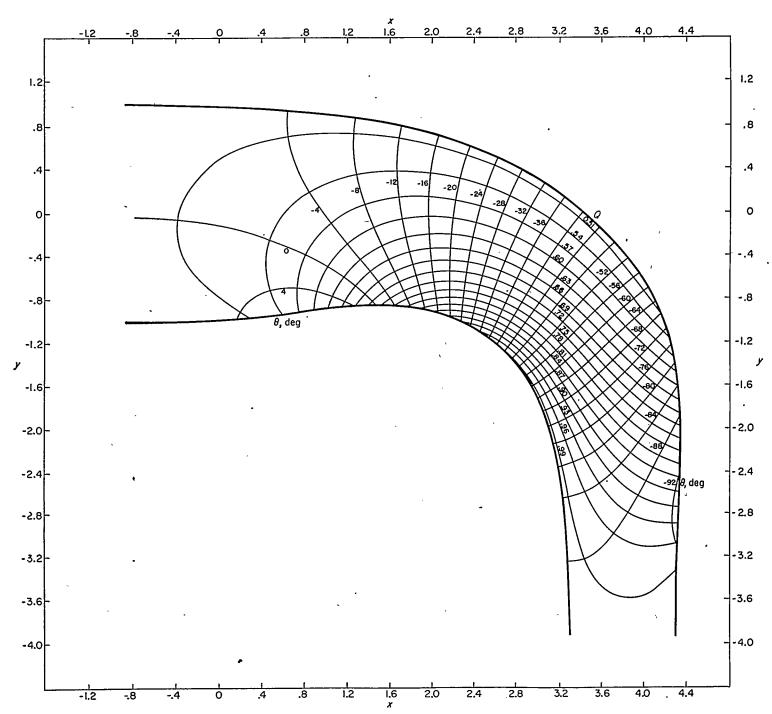


FIGURE 16.—Lines of constant velocity Q and flow direction  $\theta$  in physical xy-plane for example III. Incompressible flow; prescribed velocity given in figures 2 and 13.

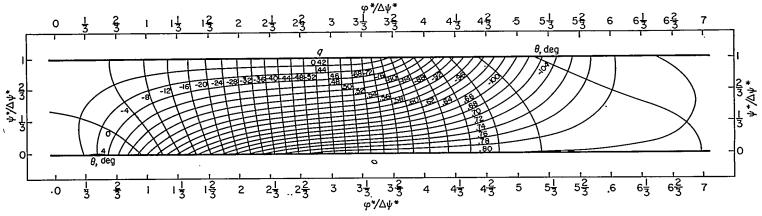


FIGURE 17.—Lines of constant velocity q and flow direction \$\theta\$ in transformed \$\varphi^\*\psi^\*\$-plane for example IV. Linearized compressible flow; prescribed velocity as function of arc length along channel walls same as for example III (fig. 2) and with qe equal to 0.80178.

turns in the opposite direction to the elbow turning angle. As usual, the streamlines and velocity-potential lines are orthogonal.

In figure 19, lines of constant q and  $\theta$  are plotted in the physical xy-plane. The lines of constant q and  $\theta$  are not, in general, orthogonal.

#### EXAMPLE V

The fifth numerical example is the design of an elbow with the same prescribed velocity Q, as a function of arc length, used in examples III and IV but for compressible flow  $(\gamma = 1.4)$ .

Prescribed velocity distribution.—The prescribed velocity distribution Q is the same as that for examples III and IV but with  $q_d$  equal to 0.79927. The variation in Q with s along one channel wall is plotted in figure 2.

Results.—The results of example V are presented in figures 20 and 21 and in tables V and VI.

In figure 20, lines of constant  $\varphi/\Delta\psi$  and  $\psi/\Delta\psi$  are plotted in the physical xy-plane (where the constant  $\Delta \psi$  is given by equation (26) and is equal to 0.71054 for  $q_d$  equal to 0.79927). The shape of the channel walls is that required to result in the prescribed velocity distribution used in examples III and IV but with compressible flow ( $\gamma=1.4$ ) and for  $q_a$  equal to 0.79927. The upstream channel width is 1.5412 times the downstream width, and the turning angle is 105.31° compared with 104.07° for linearized compressible flow (example IV) and 89.36° for incompressible flow (example III). streamlines and velocity-potential lines are orthogonal.

The shape of the elbow for compressible flow (example V, fig. 20) is nearly the same as the shape of the elbow for linearized compressible flow (example IV, fig. 18). Therefore, in figure 21 the contours of the walls for both examples are compared. The difference in contours is very small and it is concluded that, if a nonviscous gas with arbitrary  $\gamma$  (1.4, for example) were to flow through a channel designed for linearized compressible flow ( $\gamma = -1.0$ ), the resulting velocity distribution along the channel walls would be nearly the velocity distribution prescribed for the linearized compressible flow, at least if the linearized flow were selected (by the choice of  $q_a$  and  $q_b$ ) so that the densities were equal for both types of flow at the maximum and minimum velocities and if the ratio of these prescribed velocities is not too large (2:1 in the numerical examples). This conclusion is important because the design method for linearized compressible flow is considerably faster than the design method for compressible flow with  $\gamma$  other than -1.0.

# PART II

#### SOLUTION BY GREEN'S FUNCTION

In part II a method of solution for the design of twodimensional channels with prescribed velocity distributions along the walls is developed by means of the appropriate Green's function. The method applies to incompressible and linearized compressible, irrotational flow. One numerical example is presented for an accelerating elbow with linearized compressible flow and with the same prescribed conditions as example IV of part I.

#### METHOD OF SOLUTION

The method of solution by Green's function is in conjunction with a formula derived from Green's theorem.

# PRELIMINARY CONSIDERATIONS

Stream function  $\Psi$ .—In part II it is convenient to define the stream function by  $\Psi$ , where for incompressible flow

$$d\Psi = \frac{\pi}{2} d\psi \tag{39a}$$

and for linearized compressible flow ( $\gamma = -1.0$ )

$$d\Psi = \frac{\pi d\psi^*}{2\Delta\psi^*} \tag{39b}$$

For both types of flow  $\Psi$  varies from zero along the right side of the channel, when faced in the direction of flow, to  $\pi/2$ along the left side.

Velocity potential 4.—In part II it is convenient to define the velocity potential by  $\Phi$ , where for incompressible flow

$$d\Phi = \frac{\pi}{2} d\varphi \tag{40a}$$

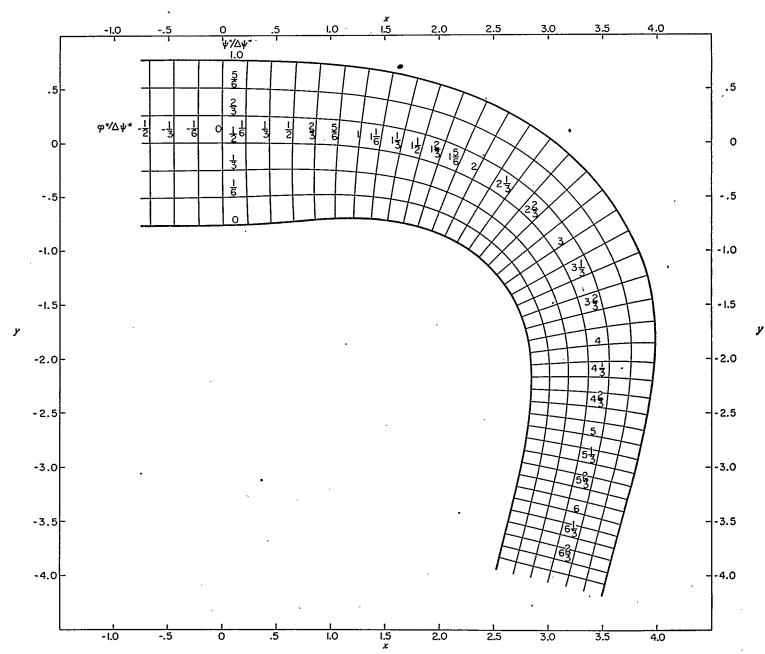


FIGURE 18.—Streamlines and velocity-potential lines in physical xy-plane for example IV. Linearized compressible flow; prescribed velocity as function of arc length along channel walls same as for example III (fig. 2) and with 22 equal to 0.80176.

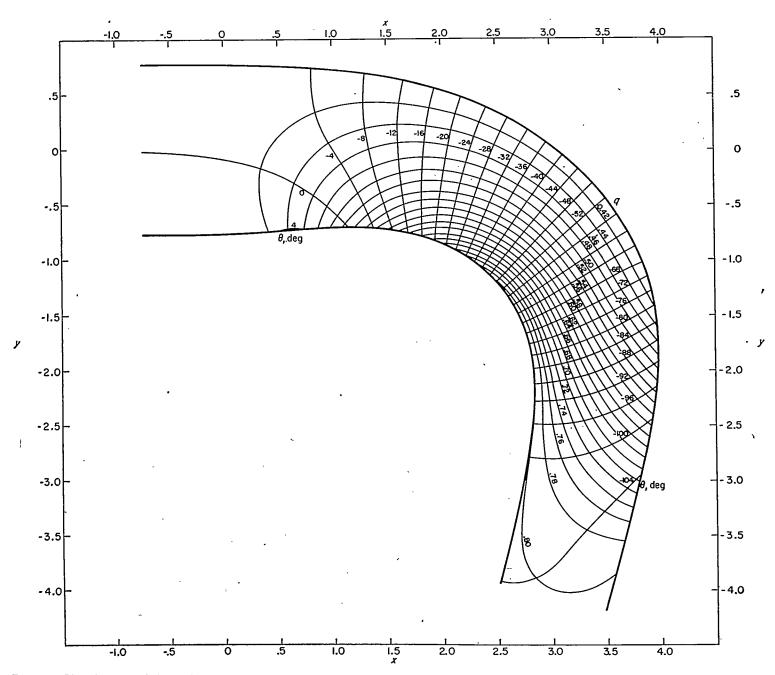


FIGURE 19.—Lines of constant velocity q and flow direction  $\theta$  in physical xy-plane for example IV. Linearized compressible flow; prescribed velocity as function of are length along channel walls same as for example III (fig. 2) and with  $q_d$  equal to 0.80176.

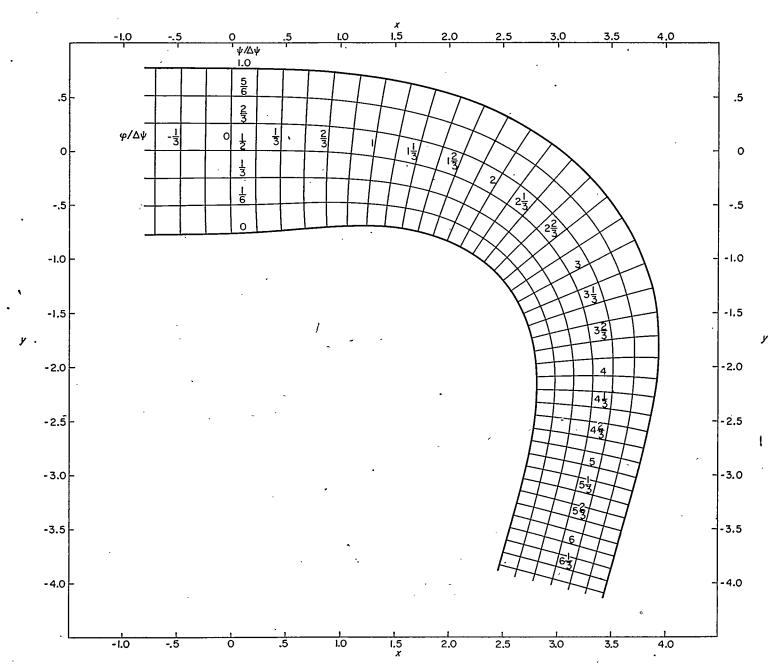


FIGURE 20.—Streamlines and velocity-potential lines in physical xy-plane for example V. Compressible flow ( $\gamma=1.4$ ); prescribed velocity as function of arc length along channel walls same as for examples III and IV (fig. 2) but with  $q_3$  equal to 0.79927.

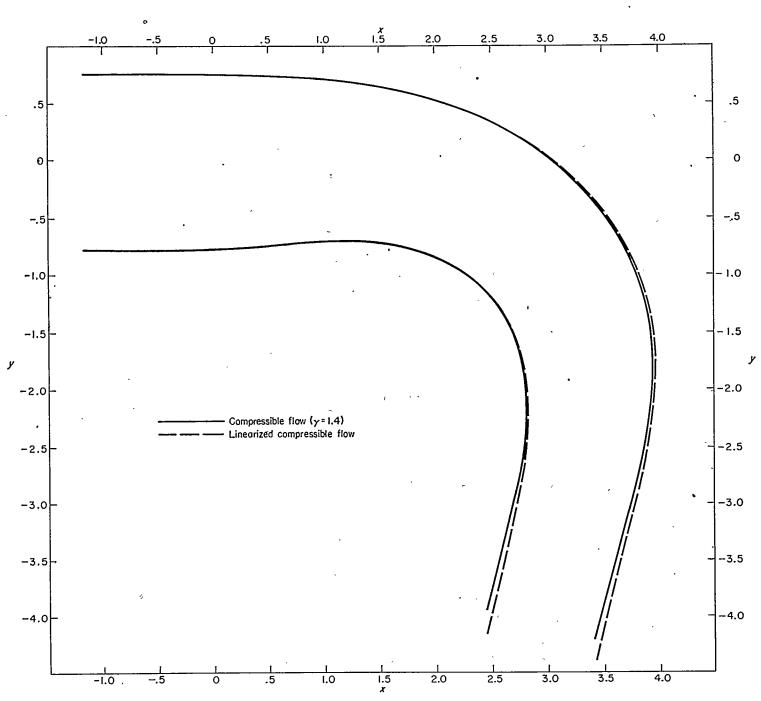


FIGURE 21.—Comparison of channel-wall shapes for compressible flow (example V) with  $\gamma$  equal to 1.4 and for linearized compressible flow (example IV) for same prescribed velocity as function of arc length along channel walls (fig. 2).

and for linearized compressible flow

$$d\Phi = \frac{\pi}{2} \frac{d\varphi^*}{\Delta \psi^*} \tag{40b}$$

Channel-wall coordinates.—From part I the distribution of channel-wall coordinates x and y along the boundaries of constant  $\Psi$  equal to 0 and  $\pi/2$  in the transformed  $\Phi\Psi$ -plane is given by

$$x = \frac{2}{\pi} \Delta \psi^* \int_{\Phi} \frac{\cos \theta}{a^*} d\Phi \qquad (41a)$$

and

$$y = \frac{2}{\pi} \Delta \psi^* \int_{\Psi} \frac{\sin \theta}{q^*} d\Phi \tag{41b}$$

for linearized compressible flow, and for incompressible flow is given by

$$x = \frac{2}{\pi} \int_{\Phi} \frac{\cos \theta}{Q} d\Phi \tag{42a}$$

and

$$y = \frac{2}{\pi} \int_{\Psi} \frac{\sin \theta}{Q} d\Phi \tag{42b}$$

where the constants of integration are selected to give known (specified) values of x or y at one value of  $\Phi$  along each boundary. Because  $q^*$  and Q are known functions of  $\Phi$  from the prescribed velocity as a function of arc length along the channel walls, the shape of the channel walls in the physical xy-plane is given by equation (41) or (42) if  $\theta$  is determined as a function of  $\Phi$  along the channel walls. In part  $\Pi$  the solution for  $\theta$  as a function of  $\Phi$  along the channel walls in the  $\Phi\Psi$ -plane is obtained by Green's function.

#### SOLUTION BY GREEN'S FUNCTION

Continuity.—From part I the continuity equation becomes in the transformed  $\Phi\Psi$ -plane

$$\frac{\partial \log_{\bullet} V}{\partial \Phi} + \frac{\partial \theta}{\partial \Psi} = 0 \tag{43a}$$

where for incompressible flow

$$V=Q$$
 (43b)

and for linearized compressible flow

$$V = \frac{q^*}{1 + \sqrt{1 + q^{*2}}} \tag{43c}$$

Irrotational motion.—From part I the equation for irrotational motion becomes in the transformed  $\Phi\Psi$ -plane

$$\frac{\partial \log_{\epsilon} V}{\partial \Psi} - \frac{\partial \theta}{\partial \Phi} = 0 \tag{44}$$

Integral equation for  $\theta(\Phi_o, \Psi_o)$ .—From equations (43a) and (44)

$$\frac{\partial^2 \theta}{\partial \Phi^2} + \frac{\partial^2 \theta}{\partial \Psi^2} = 0 \tag{45}$$

so that from appendix E the value of  $\theta$  at a point  $(\Phi_o, \Psi_o)$ 

within, or on, the channel walls in the transformed  $\Phi\Psi$ -plane is given by the integral equation

$$\theta(\Phi_o, \Psi_o) = \frac{-1}{2\pi} \int_{-\infty}^{\infty} \left[ \left( G \frac{\partial \log_e V}{\partial \Phi} \right)_{\frac{\pi}{2}} - \left( G \frac{\partial \log_e V}{\partial \Phi} \right)_0 \right] d\Phi \quad (46)$$

where the subscripts 0 and  $\frac{\pi}{2}$  refer to the channel-wall boundaries along which  $\Psi$  is 0 and  $\frac{\pi}{2}$ , respectively, and G is the Green's function of the second kind for the channel, which is an infinite strip of width  $\frac{\pi}{2}$  extending in the  $\Phi$ -direction to  $+\infty$ .

Green's function G.—The Green's function of the second kind G for the infinite channel in the  $\Phi\Psi$ -plane is given along the channel-wall boundaries ( $\Psi$  equals 0 and  $\frac{\pi}{2}$ ) by (appendix F)

$$G_{0 \text{ or } \frac{\pi}{2}} = -\log_{\epsilon} \left[ \cosh^{2}(\Phi - \Phi_{o}) - \cos^{2}(\Psi - \Psi_{o}) \right] \tag{47}$$

where  $(\Phi, \Psi)$  is any point on the channel-wall boundary and  $(\Phi_o, \Psi_o)$  is the point in the channel or on the boundary lat which  $\theta$  is to be determined.

Numerical integration for  $\theta(\Phi_o, \Psi_o)$ .—From equations (46) and (47)

$$2\pi\theta (\Phi_{o}, \Psi_{o}) = \int_{-\infty}^{\infty} \left\{ \frac{\partial \log_{o} V}{\partial \Phi} \log_{o} \left[ \cosh^{2} (\Phi - \Phi_{o}) - \sin^{2} \Psi_{o} \right] \right\}_{\frac{\pi}{2}} d (\Phi - \Phi_{o}) - \int_{-\infty}^{\infty} \left\{ \frac{\partial \log_{o} V}{\partial \Phi} \log_{o} \left[ \cosh^{2} (\Phi - \Phi_{o}) - \cos^{2} \Psi_{o} \right] \right\}_{0} d (\Phi - \Phi_{o})$$

$$(48)$$

in which the independent variable of integration has been changed from  $d\Phi$  to  $d(\Phi-\Phi_o)$  so that the origin, for purposes of integration, lies at  $\Phi_o$  rather than  $\Phi=0$ . If for small changes in  $(\Phi-\Phi_o)$ , that is, for small  $\Delta\Phi$ , the term  $\frac{\partial \log_o V}{\partial \Phi}$  may be considered constant and equal to its average value over the interval  $\Delta\Phi$ , then

$$\frac{\partial \log_{\bullet} V}{\partial \Phi} = \frac{\Delta \log_{\bullet} V}{\Delta \Phi}$$

and equation (48) becomes

$$2\pi\theta (\Phi_{o}, \Psi_{o}) = \sum_{(\Phi - \Phi_{o}) = -\infty}^{\infty} \left\{ \frac{\Delta \log_{e} V}{\Delta \Phi} \int_{(\Phi - \Phi_{o})}^{(\Phi - \Phi_{o}) + \Delta \Phi} \log_{e} \left[ \cosh^{2}(\Phi - \Phi_{o}) - \sin^{2} \Psi_{o} \right]' d \left( \Phi - \Phi_{o} \right) \right\}_{\frac{\pi}{2}}^{\infty} - \sum_{(\Phi - \Phi_{o}) = -\infty}^{\infty} \left\{ \frac{\Delta \log_{e} V}{\Delta \Phi} \int_{(\Phi - \Phi_{o})}^{(\Phi - \Phi_{o}) + \Delta \Phi} \log_{e} \left[ \cosh^{2}(\Phi - \Phi_{o}) - \cos^{2} \Psi_{o} \right] d \left( \Phi - \Phi_{o} \right) \right\}_{0}$$

$$(49)$$

where the summation sign is understood to mean that the quantity within the braces is summed over the entire range of  $(\Phi - \Phi_o)$  between  $\pm \infty$ .

Equation (49) determines  $\theta$  at any point in the flow field (channel). For a point  $(\Phi_o, \Psi_o)$  on the channel walls  $\Psi_o$  is equal to 0 or  $\pi/2$  and the integrands in equation (49) become

 $2 \log_e \cosh |(\Phi - \Phi_e)|$ 

or

$$2 \log_{o} \sinh |(\Phi - \Phi_{o})|$$

so that equation (49) becomes

$$\pi\theta(\Phi_o, \Psi_o) = \sum_{(\Phi - \Phi_o) = -\infty}^{\infty} \left[ \left( \frac{\Delta \log_e V}{\Delta \Phi} \Delta I \right)_{\frac{\pi}{2}} - \left( \frac{\Delta \log_e V}{\Delta \Phi} \Delta I \right)_0 \right]$$
(50a)

where

$$\Delta I = I_{(\Phi - \Phi_{\bullet}) + \Delta \Phi} - I_{(\Phi - \Phi)_{\bullet}} \tag{50b}$$

$$I_{\frac{\pi}{2}} = \alpha \text{ if } \Psi_o = 0$$

$$I_{\frac{\pi}{2}} = \beta \text{ if } \Psi_o = \frac{\pi}{2}$$

$$I_o = \alpha \text{ if } \Psi_o = \frac{\pi}{2}$$

$$I_o = \beta \text{ if } \Psi_o = 0$$

$$(50c)$$

where

$$\alpha = \pm \int_{0}^{\left[(\Phi - \Phi_{o})\right]} \log_{\bullet} \cosh \left| (\Phi - \Phi_{o}) \right| d \left| (\Phi - \Phi_{o}) \right| \tag{50d}$$

$$\beta = \pm \int_{0}^{|(\Phi - \Phi_{\bullet})|} \log_{\bullet} \sinh |(\Phi - \Phi_{\bullet})| d |(\Phi - \Phi_{\bullet})| \qquad (50e)$$

where the + signs apply for positive values of  $(\Phi - \Phi_o)$  and the - signs apply for negative values of  $(\Phi - \Phi_o)$ . Methods of evaluating  $\alpha$  and  $\beta$  are given in appendix G, and tabulated values are given for a wide range of  $|(\Phi - \Phi_o)|$  in table VII. Equation (50a) determines  $\theta(\Phi_o, \Psi_o)$  at any point on the channel-wall boundaries. Thus from equations (41a) and (41b) or (42a) and (42b) the coordinates for the channel-wall shape in the physical xy-plane can be determined.

# NUMERICAL PROCEDURE

The numerical procedure for the channel design solution by Green's function is the same, except for minor details, for incompressible and linearized compressible flow. The stepwise procedure is outlined as follows:

(1) For incompressible flow the velocity Q and for linearized compressible flow the velocity q, or which is the same thing the velocity Q and the constant downstream velocity  $q_d$ , are specified as functions of arc length along the channel walls

$$Q = Q(8) \tag{51a}$$

or

$$q = q(s) \tag{51b}$$

where s is arbitrarily equal to 0 at that point along one channel wall where the velocity first begins to vary.

(2) Compute V as a function of s from equations (43b) and (51a) for incompressible flow or from equations (13b), (14b), (43c), and (51b) for linearized compressible flow

$$V = V(s)$$
 (52)

(3) Compute  $\Phi$  as a function of s from equations (4) and (40a) for incompressible flow or from equations (16), (32), (40b), and (51b) for linearized compressible flow. In equation (32)  $\rho_d^*$  is obtained from equations (8a), (13a), and (14a). For arbitrary distributions of Q or q equation (40a) or (40b) is integrated numerically by using, for example, Simpson's one-third rule. Thus

$$\Phi = \Phi(s) \tag{53}$$

(4) From equations (52) and (53) V and  $\Phi$  are known functions of s so that

$$V = V(\Phi) \tag{54}$$

Thus V is a known function of  $\Phi$  along the channel-wall boundaries in the transformed  $\Phi\Psi$ -plane.

- (5) If the prescribed velocity distribution along one wall is different from that along the other, the channel will, in general, turn the flow. This turning angle  $\Delta\theta$  is given by equation (H5) in appendix H. If the turning angle is unsatisfactory, a new distribution of velocity as a function of s (eqs. (51a) and (51b)) is prescribed and steps (1) to (5) repeated until the desired value of  $\Delta\theta$  is obtained. Equation (H5) is integrated numerically by using Simpson's one-third rule, for example, and equation (54).
- (6) The channel-wall boundaries are straight parallel lines of constant  $\Psi$  equal to 0 and  $\pi/2$ , and extending to  $\pm \infty$ in the  $\Phi$ -direction. Along these boundaries of constant  $\Psi$ , a series of equally spaced points are located at each of which the flow direction  $\theta$  and the x,y-coordinates of the channel walls will be determined by numerical integration. In order to use the tables of  $\alpha$  and  $\beta$  presented in this report, the point spacing  $\Delta\Phi$  must be an even multiple of  $\pi/24$ . Thus the smallest point spacing  $\pi/24$  is equal to  $\%_2$  of the channel width  $(\pi/2)$ . For a particular prescribed velocity distribution along the channel walls the accuracy of the solution increases, and so does the amount of computing, as the point spacing is reduced. The error for a given point spacing depends on the prescribed velocity distribution, and its order of magnitude is given by the leading term of the error series of the formula used for numerical integration (table VIII, ref. 4, for example). For the numerical example presented in part  $\Pi$  of this report the point spacing  $\Delta\Phi$  was  $\pi/12$ . From equation (54)

$$\frac{\Delta \log_{\epsilon} V}{\Delta \Phi} = \frac{(\log_{\epsilon} V)_{\Phi + \Delta \Phi} - (\log_{\epsilon} V)_{\Phi}}{\Delta \Phi}$$
 (55)

where the subscripts  $\Phi$  and  $\Phi + \Delta \Phi$  refer to adjacent points along the channel boundaries.

(7) The value of  $\theta$  at each point  $(\Phi_o, \Psi_o)$  on the channel-wall boundaries is obtained from equation (50a) in which  $(\Delta \log_{\bullet} V)/\Delta \Phi$  is given by equation (55) and  $\Delta I$  is given by equations (50b), (50c), and table VII. Note that in equation

(50a) the origin has been moved to  $\Phi_o$  by changing from  $\Phi$  to  $(\Phi - \Phi_o)$ . Thus the value of  $(\Delta \log_e V)/\Delta \Phi$  for a given value of  $(\Phi - \Phi_o)$  varies with  $\Phi_o$ .

(8) The physical x,y-coordinates at each point on the channel-wall boundaries are obtained by the numerical integration of equations (42a) and (42b) for incompressible flow, or equations (41a) and (41b) for linearized compressible flow where  $\Delta \psi^*$  is given by equation (32). The constants of integration in equations (41) and (42) are selected to give known values of x and y at upstream or downstream positions where flow conditions can be considered uniform.

# NUMERICAL EXAMPLE

The channel design method of part II has been applied to the design of an elbow for the same conditions as example IV of part I. The design is for an accelerating elbow with no local decelerations of the prescribed velocities along the channel walls and with linearized compressible flow.

'Prescribed velocity distribution.—The prescribed velocity distribution along the channel walls is the same as that for example IV of part I. The prescribed velocity as a function of  $\Phi$  is plotted in figure 22.

Results.—As indicated in table VIII, the elbow design resulting from the prescribed velocities given in figure 22 is the same as that obtained by relaxation methods (fig. 21) for the same prescribed conditions (example IV, part I).

The solution obtained by Green's function (part II) required one experienced computer 3 days, whereas the solution by relaxation methods (part I) required about 10 days. The relaxation solutions provide additional information, such as the distribution of velocity across the channel; but for the most part this additional information is of secondary importance, and the design of channels by Green's function is more rapid and therefore to be preferred over the design by relaxation methods.

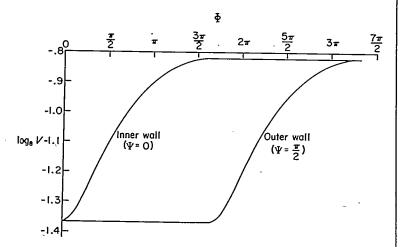


Figure 22.—Variation in prescribed values of  $\log_{\bullet}V$  with  $\Phi$  along channel walls of numerical example in part II.

# SUMMARY OF RESULTS AND CONCLUSIONS

A general method of design is developed for twodimensional unbranched channels with prescribed velocities as a function of arc length along the channel walls. The method is developed for both compressible and incompressible, irrotational, nonviscous flow and applies to the design of elbows, diffusers, nozzles, and so forth. Two types of compressible flow are considered: the general type with arbitrary value for the ratio of specific heats  $\gamma$  (1.4, for example) and the linearized type in which  $\gamma$  is equal to -1.0. In part I solutions are obtained by relaxation methods on a transformed plane the coordinates of which are the streamlines and velocity-potential lines in the physical plane; in part II solutions are obtained by a Green's function. The method of solution in part I gives complete information concerning the flow throughout the channel, whereas the method of solution in part II gives the channelwall coordinates only.

Five numerical examples are given in part I and the results are presented by (1) lines of constant velocity and flow direction or lines of constant physical coordinates in the transformed plane and (2) streamlines and velocity-potential lines or lines of constant velocity and flow direction in the physical plane. Among the five examples are three elbow designs for the same prescribed velocity as a function of arc length along the channel walls but with incompressible, linearized compressible, and compressible flow. The numerical results of these three elbow designs are tabulated to enable a detailed comparison of the three designs.

The shapes of the elbows for compressible flow and for linearized compressible flow are very nearly the same; and it is concluded that, if a nonviscous gas with arbitrary  $\gamma$  (1.4, for example) were to flow through a channel designed for linearized compressible flow ( $\gamma = -1.0$ ), the resulting velocity distribution along the channel walls would be nearly the velocity distribution prescribed for the linearized compressible flow. This conclusion is important because the design method for linearized compressible flow is considerably faster than that for compressible flow.

One numerical example is presented in part II for an accelerating elbow with linearized compressible flow. The elbow shape obtained from the solution by Green's function in part II is the same as that obtained from a solution by relaxation methods in part I for the same prescribed conditions. The time required for the calculations was considerably less for the solution by Green's function.

Lewis Flight Propulsion Laboratory
National Advisory Committee for Aeronautics
Cleveland, Ohio, July 25, 1951

# APPENDIX A

# SYMBOLS

The following	g symbols are used in this report:	$\theta$	flow direction in physical xy-plane (meas- ured in counterclockwise direction from
A, $B$ , $C$ , $D$	coefficients, equation (29)		positive x-axis)
A, B	arbitrary constants, equation (C1a)	$\Delta  heta$	channel turning angle, equation (12)
$B_1, B_3, \ldots$	Bernoulli's numbers	ρ	density (expressed as ratio of stagnation
C	constant, equation (E3)		density)
G	Green's function of the second kind, equa-	ρ*	density in linearized compressible flow and
7	tions (E2) and (47)		related to $\rho$ by equation (13a)
I ,	integral ( $\alpha$ or $\beta$ )	Φ	velocity potential used as Cartesian co-
$egin{array}{c} k_1 \ k_2 \end{array}$	coefficient, equation (14a) coefficient, equation (14b)		ordinate in transformed ΦΨ-plane and
11.2 1	length of closed boundary		related to $\varphi$ or $\varphi^*$ by equation (40a) or
n	distance in xy-plane measured normal to	1 +	(40b), respectively
10	direction of flow (expressed as ratio of	$\varphi$ and $\varphi^*$	velocity potential for incompressible and
	characteristic length equal to channel		linearized compressible flow, respectively,
	width downstream at infinity)	, iTe	equations (4) and (16)
p	static pressure (expressed as ratio of stag-	Ψ ,	stream function used as Cartesian coordi-
*	nation density multiplied by stagnation		nate in transformed $\Phi\Psi$ -plane and related to $\psi$ or $\psi^*$ by equation (39a) or (39b),
	speed of sound squared)		respectively
Q	velocity (expressed as ratio of characteristic	$\psi$ and $\psi^*$	stream function for incompressible and
	velocity equal to constant channel veloc-	y und y	linearized compressible flow, respectively,
	ity downstream at infinity)		equations (3) and (15)
q	velocity (expressed as ratio of stagnation	Δψ*	boundary value of $\psi^*$ , for linearized com-
	speed of sound)	•	pressible flow, along left channel wall
$q^*$	velocity used in linearized compressible		when faced in the direction of flow,
	flow and related to $q$ by equation (13b)		equation (32)
r	distance from any point in ΦΨ-plane to	ω	any harmonic function in ΦΨ-plane
	point $(\Phi_o, \Psi_o)$ at which logarithmic singu-	Subscripts:	
_	larity exists	<i>a,b</i> ·	quantities related to two velocities (qa and
8	distance in xy-plane measured along direc- tion of flow (expressed as ratio of char-	1	$q_b$ , respectively) for which density given
	acteristic length equal to channel width		by equation (8a) is equal to density $\rho$
	downstream at infinity)	_	given by equations (13), (13a), and (13b)
u	velocity parameter related to $q^*$ by equa-	$\dot{q}$	conditions downstream at infinity
w	tion (18)	0	point in $\Phi\Psi$ -plane at which $\theta$ is determined
V	velocity parameter defined by equations	u 	conditions upstream at infinity
•	(43b) and (43c) for incompressible and	Δψ*	left channel wall, when faced in direction of
	linearized compressible flow, respectively	$(\Phi - \Phi_o)$	flow, along which $\psi^*$ is equal to $\Delta \psi^*$ point at $(\Phi - \Phi_o)$ on either channel-wall
$w$ , $w_1$ , $w_2$	complex functions defined by equations	· (4-40)	boundary
, -, -	(F3), (F1a), and (F2a), respectively	$(\Phi - \Phi_o) + \Delta \Phi$	point at $[(\Phi - \Phi_o) + \Delta \Phi]$ on either channel-
x, y	Cartesian coordinates in physical plane	(0) 1	wall boundary
	(expressed as ratios of characteristic	$\varphi, \psi, \varphi^*, \psi^*$	along lines of constant $\varphi, \psi, \varphi^*$ , and $\psi^*$ , re-
	length equal to channel width down-	•	spectively
	stream at infinity)	0	right channel wall, when faced in direction
<u>z</u>	complex coordinate, equation (F1b)		of flow, along which $\Psi$ , $\psi$ , or $\psi^*$ is equal
Z	conjugate of z		to 0
α	integral, equation (50d)	1.0	left channel wall, when faced in direction
β	integral, equation (50e)		of flow, along which $\psi$ is equal to 1.0
$oldsymbol{\gamma}{\Delta}$	ratio of specific heats finite increment	$\frac{\pi}{2}$	left channel wall, when faced in direction
δ	increment of	_ ^	of flow, along which $\Psi$ is equal to $\frac{\pi}{2}$
-		•	-

# APPENDIX B

# EQUATIONS OF CONTINUITY AND IRROTATIONAL FLUID MOTION IN TERMS OF TRANSFORMED $\varphi$ , $\psi$ -COORDINATES

Consider the two-dimensional irrotational motion of a fluid particle in the physical xy-plane. The fluid particle is defined by adjacent streamlines (constant  $\psi$ ) and velocity-potential lines (constant  $\varphi$ ) spaced  $\delta n$  and  $\delta s$  apart as indicated in figure 23. The velocity Q is parallel to the streamlines and normal to the velocity-potential lines.

Continuity.—From continuity considerations of the fluid particle in figure 23

or  $\frac{\partial \log_{\epsilon} \rho}{\partial s} + \frac{\partial \log_{\epsilon} Q}{\partial s} + \frac{1}{\delta n} \frac{\partial (\delta n)}{\partial s} = 0$  (B1)

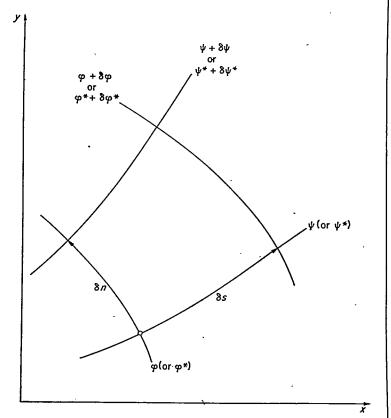


FIGURE 23.—Fluid particle bounded by streamlines and velocity-potential lines in physical rs-plane.

But, from geometrical considerations (ref. 5, p. 167, for example)

$$\frac{1}{\delta n} \frac{\partial (\delta n)}{\partial s} = \frac{\partial \theta}{\partial n}$$
 (B2a)

and

$$\frac{1}{\delta s} \frac{\partial (\delta s)}{\partial n} = -\frac{\partial \theta}{\partial s}$$
 (B2b)

so that equation (B1) becomes

$$\frac{\partial \log_{\epsilon} \rho}{\partial s} + \frac{\partial \log_{\epsilon} Q}{\partial s} + \frac{\partial \theta}{\partial n} = 0$$

or

$$\underbrace{\frac{\partial \, \log_{\epsilon} \, \rho}{\partial \varphi} \, \frac{d\varphi}{ds} + \frac{\partial \, \log_{\epsilon} \, Q}{\partial \varphi} \, \frac{d\varphi}{ds} + \frac{\partial \theta}{\partial \psi} \, \frac{d\psi}{dn}}_{=0} = 0$$

which, combined with equations (3) and (4), becomes

$$\frac{1}{\rho} \left( \frac{\partial \log_{\bullet} \rho}{\partial \omega} + \frac{\partial \log_{\bullet} Q}{\partial \omega} \right) + \frac{\partial \theta}{\partial \psi} = 0$$
 (5)

Equation (5) is the continuity equation expressed in terms of  $\varphi, \psi$ -coordinates.

Irrotational fluid motion.—For irrotational motion of the fluid particle in figure 23

$$\frac{\partial}{\partial n} (Q \delta s) = 0$$

01

$$\frac{\partial \log_{\bullet} Q}{\partial n} + \frac{1}{\delta s} \frac{\partial (\delta s)}{\partial n} = 0$$
 (B3)

But, from equations (B2b) and (B3)

$$\frac{\partial \log_{\bullet} Q}{\partial n} - \frac{\partial \theta}{\partial s} = 0$$

or

$$\frac{\partial \log_{\bullet} Q}{\partial \psi} \frac{d\psi}{dn} - \frac{\partial \theta}{\partial \omega} \frac{d\varphi}{ds} = 0$$

which, combined with equations (3) and (4), becomes

$$\rho \frac{\partial \log_s Q}{\partial \psi} - \frac{\partial \theta}{\partial \varphi} = 0 \tag{6}$$

Equation (6) is the equation for irrotational fluid motion expressed in terms of the  $\varphi,\psi$ -coordinates.

# APPENDIX C

# RELATION BETWEEN VELOCITY AND DENSITY ASSUMING LINEAR VARIATION IN PRESSURE WITH SPECIFIC VOLUME

The approximate, linear relation between pressure p and specific volume  $1/\rho$  first suggested by Chaplygin (ref. 6) is given by

$$p = A - \frac{B}{a}$$
 (C1a)

from which

$$\frac{dp}{d\rho} = \frac{B}{\rho^2} \tag{C1b}$$

where A and B are arbitrary constants.

If p denotes the static pressure expressed as a ratio of the stagnation density multiplied by the stagnation speed of sound squared, Bernoulli's equation is

$$\frac{dp}{dq} + q dq = 0$$

which combined with equation (C1b) integrates to give the approximate relation between velocity and density

$$\frac{B}{2\rho^2} - \frac{q^2}{2} = \text{constant} \tag{C2}$$

For convenience equation (C2) can be written as

$$\frac{1}{\rho^{*2}} - q^{*2} = 1$$

or

$$\rho^* = (1 + q^{*2})^{-1/2} \tag{13}$$

where

$$\rho^* = k_1 \rho \tag{13a}$$

and

$$q^* = k_2 q \tag{13b}$$

The constants  $k_1$  and  $k_2$  replace the two arbitrary constants in equation (C2), and their values are determined so that for any two arbitrary values of q (designated by  $q_a$  and  $q_b$ ) the values of  $\rho$  given by equation (13) equal the values of  $\rho$ given by equation (8a). Thus the values of  $\rho$  given by equation (13) for q equal to  $q_a$  or  $q_b$  are correct; for all other values of q the values of  $\rho$  are approximate. The constants  $k_1$  and  $k_2$  are determined from the conditions

$$\begin{array}{l}
\rho_a^* = k_1 \rho_a \\
q_a^* = k_2 q_a \\
\rho_b^* = k_1 \rho_b \\
q_b^* = k_2 q_b
\end{array} (C3)$$

From equation (13) and the conditions given by equation (C3)

$$k_{1} = \frac{1}{\rho_{a}} \sqrt{\frac{1 - \left(\frac{\rho_{a} q_{a}}{\rho_{b} q_{b}}\right)^{2}}{1 - \left(\frac{q_{a}}{q_{b}}\right)^{2}}}$$
(14a)

and

$$k_2 = \frac{1}{q_b} \sqrt{\frac{\left(\frac{\rho_a}{\rho_b}\right)^2 - 1}{1 - \left(\frac{\rho_a q_a}{\rho_b q_b}\right)^2}} \tag{14b}$$

where  $\rho_a$  and  $\rho_b$  are determined by equation (8a) for the selected values of  $q_a$  and  $q_b$ , respectively.

The values of  $q_a$  and  $q_b$  might, for example, be selected to equal the maximum and minimum values of q (which values of q must occur on the channel walls and are therefore known). Also, the values of  $q_a$  and  $q_b$  might be selected to equal the upstream and downstream velocities  $q_a$  and  $q_d$ . In this case the upstream and downstream channel widths would then satisfy continuity for a gas with the correct value of  $\gamma$  (1.4, for example). If the upstream and downstream velocities are equal, their value and the value of some other velocity (the maximum or minimum velocity, for example) can be selected for  $q_a$  and  $q_b$ ; or, if desired,  $q_a$  can be equal to  $q_b$ , in which case if

$$q_a = q + \epsilon$$
 where  $\epsilon \rightarrow 0$   
 $q_b = q$ 

it can be shown from equations (14a) and (14b) that

$$k_1 = \frac{1}{\rho} \sqrt{\frac{1 - \frac{\gamma + 1}{2} q^2}{1 - \frac{\gamma - 1}{2} q^2}}$$
 (C4a)

and

$$k_2 = \sqrt{\frac{1}{1 - \frac{\gamma + 1}{2} q^2}}$$
 (C4b)

This latter case, in which  $q_a=q_b=q$ , corresponds to the method used by Chaplygin (ref. 6) and Kármán-Tsien (ref. 8) in which the correct relation between p and  $\frac{1}{\rho}$  is replaced by a straight line (eq. (C1a)) that is tangent to the correct relation at one point (where  $q_a=q_b$ ).

# APPENDIX D

# EQUATIONS OF CONTINUITY AND IRROTATIONAL FLUID MOTION IN TERMS OF TRANSFORMED $\varphi^*$ , $\psi^*$ -COORDINATES

Consider the two-dimensional irrotational motion of a fluid particle in the physical xy-plane. The fluid particle is defined by adjacent streamlines (constant  $\psi^*$ ) and velocity-potential lines (constant  $\varphi^*$ ) spaced  $\delta n$  and  $\delta s$  apart as indicated in figure 23. The velocity  $q^*$  is parallel to the streamlines and normal to the velocity-potential lines.

Continuity.—From continuity considerations of the fluid particle in figure 23

$$\frac{\partial}{\partial s} \left( \rho^* q^* \, \delta n \right) = 0$$

or

$$\frac{\partial \log_{\epsilon} \rho^{*}}{\partial s} + \frac{\partial \log_{\epsilon} q^{*}}{\partial s} + \frac{1}{\delta n} \frac{\partial (\delta n)}{\partial s} = 0$$

which combined with equation (B2a) becomes

$$\frac{\partial \log_{\bullet} \rho^{*}}{\partial \varphi^{*}} \frac{d\varphi^{*}}{ds} + \frac{\partial \log_{\bullet} q^{*}}{\partial \varphi^{*}} \frac{d\varphi^{*}}{ds} + \frac{\partial \theta}{\partial \psi^{*}} \frac{d\psi^{*}}{dn} = 0$$

or, from equations (15) and (16)

$$\frac{1}{\rho^*} \left( \frac{\partial \log_{\bullet} \rho^*}{\partial \varphi^*} + \frac{\partial \log_{\bullet} q^*}{\partial \varphi^*} \right) + \frac{\partial \theta}{\partial \psi^*} = 0$$
 (D1)

But, from equation (13)

$$\frac{1}{\rho^*} \frac{\partial \log_{\epsilon} \rho^*}{\partial \varphi^*} = \frac{-q^{*2}}{\sqrt{1+q^{*2}}} \frac{\partial \log_{\epsilon} q^*}{\partial \varphi^*}$$

so that equation (D1) becomes

$$\frac{1}{\sqrt{1+q^{*2}}} \frac{\partial \log_{\theta} q^{*}}{\partial \varphi^{*}} + \frac{\partial \theta}{\partial \psi^{*}} = 0$$
 (D2)

Finally, if

$$u = \frac{q^*}{1 + \sqrt{1 + q^{*2}}} \tag{18}$$

then

$$\frac{\partial \log_e q^*}{\sqrt{1+q^{*2}}} = \partial \log_e u \tag{D3}$$

so that equation (D2) becomes

$$\frac{\partial \log_{\epsilon} u}{\partial \varphi^*} + \frac{\partial \theta}{\partial \psi^*} = 0 \tag{17}$$

Equation (17) is the continuity equation expressed in terms of  $\varphi^*, \psi^*$ -coordinates and  $\log_e u$ .

Irrotational fluid motion.—For irrotational motion of the fluid particle in figure 23

$$\frac{\partial}{\partial n} (q^* \delta s) = 0$$

OI

$$\frac{\partial \log_{\delta} q^*}{\partial n} + \frac{1}{\delta s} \frac{\partial (\delta s)}{\partial n} = 0$$

which combined with equation (B2b) becomes

$$\frac{\partial \log_s q^*}{\partial \psi^*} \frac{d\psi^*}{dn} - \frac{\partial \theta}{\partial \varphi^*} \frac{d\varphi^*}{ds} = 0$$

or, from equations (13), (15), and (16)

$$\frac{1}{\sqrt{1+q^{*2}}} \frac{\partial \log_{\epsilon} q^{*}}{\partial \psi^{*}} - \frac{\partial \theta}{\partial \varphi^{*}} = 0$$
 (D4)

Finally, from equations (D3) and (D4)

$$\frac{\partial \log_{\bullet} u}{\partial \psi^{*}} - \frac{\partial \theta}{\partial \varphi^{*}} = 0 \tag{20}$$

Equation (20) is the equation for irrotational fluid motion expressed in terms of  $\varphi^*$ ,  $\psi^*$ -coordinates and  $\log_{\bullet} u$ .

# APPENDIX E

# INTEGRAL EQUATION FOR $\theta(\Phi_o, \Psi_o)$

If the distribution of the angle  $\theta(\Phi, \Psi)$  in the transformed  $\Phi\Psi$ -plane is harmonic, that is, satisfies equation (45) within and on the channel walls  $\left(\Psi\right)$  equals 0 and  $\frac{\pi}{2}$ , then from Green's theorem and the theorem of mean value it can be shown that the value of  $\theta$  at a point  $(\Phi_0, \Psi_0)$  within (or on) the channel walls is given by (ref. 9, p. 204, for example)

$$\theta(\Phi_o, \Psi_o) = \frac{1}{2\pi} \left[ \int_{-\infty}^{\infty} \left( \theta \frac{\partial G}{\partial \Psi} - G \frac{\partial \theta}{\partial \Psi} \right)_0 d\Phi - \int_{\infty}^{-\infty} \left( -\theta \frac{\partial G}{\partial \Psi} + G \frac{\partial \theta}{\partial \Psi} \right)_{\frac{\pi}{2}} d\Phi \right]$$
(E1)

where the two integrals on the right side of equation (E1) represent the line integral around the channel walls in the counterclockwise direction with the signs adjusted so that  $\frac{\partial}{\partial \Psi}$  represents the inner normal to the path of integration.

The function  $G(\Phi, \Psi)$  in equation (E1) is of the form (ref. 9, p. 204)

$$G(\Phi, \Psi) = \log_{\sigma} \frac{1}{r} + \omega(\Phi, \Psi)$$
 (E2)

where r is the distance from any point  $(\Phi, \Psi)$  to the point  $(\Phi_o, \Psi_o)$  and where  $\omega(\Phi, \Psi)$  is an arbitrary function that is harmonic within and on the channel walls. (Thus from equation (E2),  $G(\Phi, \Psi)$  is harmonic within and on the channel walls except at the point  $(\Phi_o, \Psi_o)$  where a logarithmic singularity exists.) Because the harmonic function  $\omega(\Phi, \Psi)$  is arbitrary, the function  $G(\Phi, \Psi)$  can be selected so that along

the channel-wall boundaries  $\left(\Psi \text{ equals 0 and } \frac{\pi}{2}\right) \frac{\partial G}{\partial \Psi}$  is a constant c given by the following equation (obtained from notes presented by Tamarkin and Feller in the 1941 Summer Session for Advanced Instruction and Research in Mechanics at Brown Univ.):

$$c = \frac{2\pi}{I} \tag{E3}$$

where l is the length of the path along which the line integral is taken. For the path under consideration l is infinite and therefore  $G(\Phi, \Psi)$  can be selected so that  $\frac{\partial G}{\partial \Psi}$  is zero along the channel walls. A function with this property is a Green's function of the second kind. Equation (E1) becomes

$$\theta \left( \Phi_o, \Psi_o \right) = \frac{1}{2\pi} \int_{-\infty}^{\infty} \left[ \left( G \frac{\partial \theta}{\partial \Psi} \right)_{\frac{\pi}{2}} - \left( G \frac{\partial \theta}{\partial \Psi} \right)_0 \right] d\Phi$$

or, combined with equation (43a)

$$\theta \left( \Phi_o, \Psi_o \right) = \frac{-1}{2\pi} \int_{-\infty}^{\infty} \left[ \left( G \frac{\partial \log_e V}{\partial \Phi} \right)_{\frac{\pi}{2}} - \left( G \frac{\partial \log_e V}{\partial \Phi} \right)_0 \right] d\Phi \tag{46}$$

Along the channel walls  $\frac{\partial \log_{\bullet} V}{\partial \Phi}$  is known from the prescribed velocity distribution so that, after the proper Green's function G has been determined (appendix F), equation (46) determines the value of  $\theta$  at any point  $(\Phi_o, \Psi_o)$ . The value of  $\theta(\Phi_o, \Psi_o)$  given by equation (46) can be adjusted by an arbitrary constant of integration to give a specified value of  $\theta$  at one point in the flow field.

# GREEN'S FUNCTION OF SECOND KIND

From appendix E Green's function of the second kind G satisfies the condition

$$\frac{\partial G}{\partial \Psi} = 0$$

along the channel walls, which are straight and parallel boundaries  $\left(\Psi \text{ equals } 0 \text{ and } \frac{\pi}{2}\right)$  extending to  $\pm \infty$  in the  $\Phi$ direction, and satisfies the equation

$$\frac{\partial^2 G}{\partial \Phi^2} + \frac{\partial^2 G}{\partial \Psi^2} = 0$$

everywhere in the channel except at the point  $(\Phi_o, \Psi_o)$ where G has a logarithmic pole. For these conditions the Green's function G can be obtained by analogy from the velocity potential for incompressible flow into a point sink at  $(\Phi_o, \Psi_o)$  between straight parallel boundaries at  $\Psi$  equal to 0 The logarithmic pole for G at  $(\Phi_o, \Psi_o)$  corresponds to the point sink, and the condition  $\frac{\partial G}{\partial \Psi}$ =0 at the boundaries corresponds to zero velocity, that is, no flow normal to the

boundaries. The velocity potential for fluid flow with the boundary conditions just described is obtained from two infinite series of point sinks with the sinks of each series spaced  $\pi$ distance apart in the Y-direction and the two series arranged by the method of images in such a manner that no flow crosses the boundaries, that is,  $\frac{\partial G}{\partial \Psi} = 0$ . This arrangement of point sinks is shown in figure 24.

The complex function  $w_1$  for the first infinite series of point sinks is given by (ref. 10, p. 112, for example)

$$w_1 = -\log_{\theta} \sinh (z - z_{\theta}) \tag{F1a}$$

where

$$z = \Phi + i\Psi$$
 (F1b)

The complex function  $w_2$  for the second infinite series of point sinks (mirror image of the first series in order to prevent flow across the boundaries  $\Psi$  equals 0 and  $\frac{\pi}{2}$ ) is given by

$$w_2 = -\log_e \sinh (z - \overline{z}_e)$$
 (F2a)

where

$$\overline{z} = \Phi - i\Psi$$
 (F2b)

The complex function w for the combined flow becomes from equations (F1a) to (F2b)

$$w=w_1+w_2=-\log_o \sinh \left[(\Phi-\Phi_o)+i(\Psi-\Psi_o)\right]-$$
$$\log_o \sinh \left[(\Phi-\Phi_o)+i(\Psi+\Psi_o)\right] \tag{F3}$$

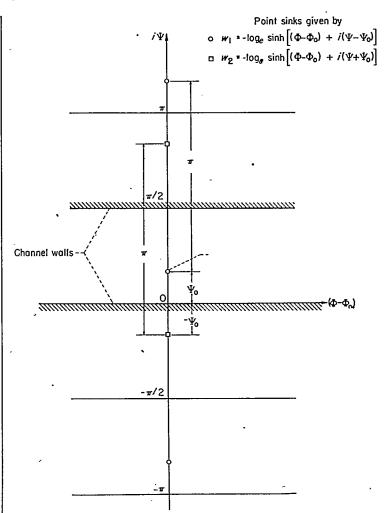


FIGURE 24.—Two infinite series of point sinks required in the development of Green's function of the second kind G.

The Green's function of the second kind G corresponds to the velocity potential for the incompressible flow and is therefore given by the real part of equation (F3)

$$G = -\frac{1}{2} \log_{\bullet} \left[ \cosh^{2} (\Phi - \Phi_{o}) - \cos^{2} (\Psi - \Psi_{o}) \right] \left[ \cosh^{2} (\Phi - \Phi_{o}) - \cos^{2} (\Psi + \Psi_{o}) \right]$$

$$(F4)$$

But along the channel walls  $\Psi$  is equal to 0 or  $\frac{\pi}{2}$  so that

$$\cos^2(\Psi + \Psi_o) = \cos^2(\Psi - \Psi_o)$$

and equation (F4) becomes

$$G_{0 \text{ or } \frac{\pi}{2}} = -\log_{\delta} \left[ \cosh^{2} \left( \Phi - \Phi_{o} \right) - \cos^{2} \left( \Psi - \Psi_{o} \right) \right] \tag{47}$$

Equation (47) gives the Green's function of the second kind along the channel walls (straight parallel lines of constant \Psi equal to 0 and  $\frac{\pi}{2}$  and extending to  $\pm \infty$  in the  $\Phi$ -direction).

# APPENDIX G

#### EVALUATION OF α AND β

Several techniques, depending on the magnitude of the upper limit  $|(\Phi - \Phi_o)|$ , were used to evaluate the integrals  $\alpha$  and  $\beta$  given by equations (50d) and (50e). Each integral is treated separately in this appendix, and the values of  $(\Phi - \Phi_o)$  for the upper limit  $|(\Phi - \Phi_o)|$  are considered positive. For negative values of  $(\Phi - \Phi_o)$  the magnitudes of I (that is, of  $\alpha$  or  $\beta$ ) are equal for corresponding values of  $|(\Phi - \Phi_o)|$  but opposite in sign. As a result the values of  $\Delta I$  have the same sign.

#### INTEGRAL a

Small and medium values of  $(\Phi - \Phi_0)$ .—For small and medium values of the upper limit of integration  $(\Phi - \Phi_0)$  in equation (50d), that is, for  $0 \le (\Phi - \Phi_0) \le 60\pi/24$ , the integral  $\alpha$  is evaluated by Simpson's one-third rule using increments of  $(\Phi - \Phi_0)$  equal to  $\pi/48$ .

Large values of  $(\Phi - \Phi_o)$ .—For large values of  $(\Phi - \Phi_o)$ , that is, for  $(\Phi - \Phi_o) > 60\pi/24$ , the integrand in equation (50d) becomes

$$\log_e \cosh (\Phi - \Phi_o) \approx (\Phi - \Phi_o) - \log_e 2$$
 (G1)

so that equation (50d) becomes

$$\alpha \approx \int_{0}^{60\pi/24} \log_{e} \cosh (\Phi - \Phi_{o}) d(\Phi - \Phi_{o}) + \int_{60\pi/24}^{(\Phi - \Phi_{o})} [(\Phi - \Phi_{o}) - \log_{e} 2] d(\Phi - \Phi_{o})$$

$$\approx 25.809782 + \left[ \frac{(\Phi - \Phi_{o})^{2}}{2} - 0.693147(\Phi - \Phi_{o}) - 25.398552 \right]$$

$$\approx 0.411230 - 0.693147(\Phi - \Phi_{o}) + \frac{1}{2} (\Phi - \Phi_{o})^{2}$$
 (G2)

Equation (G2) gives values of  $\alpha$  for values of  $(\Phi - \Phi_o)$  equal to or greater than  $60\pi/24$ . Values of the integral  $\alpha$  are tabulated in table VII for a range of  $|(\Phi - \Phi_o)|$  between 0 and  $100\pi/24$  in increments of  $\pi/24$ . For negative values of  $(\Phi - \Phi_o)$  the sign of  $\alpha$  is negative.

### INTEGRAL B

Small values of  $(\Phi - \Phi_0)$ .—For  $(\Phi - \Phi_0)$  equal to zero the integrand of equation (50e) becomes infinite so that Simpson's one-third rule cannot be used to evaluate  $\beta$  in this region of  $(\Phi - \Phi_0)$ , as was done for  $\alpha$ . However, equation (50e) integrates by parts to give

$$\int_{0}^{(\Phi-\Phi_{o})} \log_{\bullet} \sinh (\Phi-\Phi_{o}) d(\Phi-\Phi_{o}) = (\Phi-\Phi_{o}) \log_{\bullet} \sinh (\Phi-\Phi_{o}) - \int_{0}^{(\Phi-\Phi_{o})} (\Phi-\Phi_{o}) \coth (\Phi-\Phi_{o}) d(\Phi-\Phi_{o})$$
 (G3)

where the integrand  $(\Phi - \Phi_o)$  ctnh  $(\Phi - \Phi_o)$  on the right side of equation (G3) can be expanded in the following series form:

$$(\Phi - \Phi_o) \coth (\Phi - \Phi_o) = 1 + \frac{2^2 B_1 (\Phi - \Phi_o)^2}{2!} - \frac{2^4 B_3 (\Phi - \Phi_o)^4}{4!} + \frac{2^8 B_5 (\Phi - \Phi_o)^8}{6!} - \frac{2^8 B_7 (\Phi - \Phi_o)^8}{8!} + \frac{2^{10} B_9 (\Phi - \Phi_o)^{10}}{10!} - \frac{2^{12} B_{11} (\Phi - \Phi_o)^{12}}{12!} + \dots$$
(G4)

where  $B_1$ ,  $B_3$ , and so forth, are Bernoulli's numbers (ref. 11, p. 90, for example). From equations (G3) and (G4)

$$\beta = (\Phi - \Phi_o) \log_e \sinh (\Phi - \Phi_o) - (\Phi - \Phi_o) - \frac{(\Phi - \Phi_o)^3}{9} + \frac{(\Phi - \Phi_o)^5}{225} - \frac{2(\Phi - \Phi_o)^7}{6615} + \frac{(\Phi - \Phi_o)^9}{42,525} - \frac{2(\Phi - \Phi_o)^{11}}{1,029,105} + \frac{1382(\Phi - \Phi_o)^{13}}{8,300,667,375} - \dots$$
 (G5)

Equation (G5) was used to obtain  $\beta$  as a function of  $(\Phi - \Phi_o)$  for  $0 \le (\Phi - \Phi_o) \le 8\pi/24$ .

Medium values of  $(\Phi - \Phi_o)$ .—For medium values of the upper limit of integration  $(\Phi - \Phi_o)$  in equation (50e), that is, for  $8\pi/24 < (\Phi - \Phi_o) \le 60\pi/24$ , the integral  $\beta$  is evaluated by Simpson's one-third rule as was done for  $\alpha$ .

Large values of  $(\Phi - \Phi_o)$ .—For large values of  $(\Phi - \Phi_o)$ , that is, for  $(\Phi - \Phi_o) > 60\pi/24$ , the integrand in equation (50e) becomes

$$\log_{\bullet} \sinh (\Phi + \Phi_o) \approx (\Phi - \Phi_o) - \log_{\bullet} 2$$
 (G6) so that equation (50e) becomes

$$\begin{split} \beta &\approx \int_{0}^{60\pi/24} \log_{s} \sinh \left(\Phi - \Phi_{o}\right) \ d(\Phi - \Phi_{o}) + \\ &\int_{60\pi/24}^{(\Phi - \Phi_{o})} \left[ (\Phi - \Phi_{o}) - \log_{s} 2 \right] \ d\left(\Phi - \Phi_{o}\right) \\ &\approx 24.576082 + \left[ \frac{(\Phi - \Phi_{o})^{2}}{2} - 0.693147 \left(\Phi - \Phi_{o}\right) - 25.398552 \right] \\ &\approx -0.822470 - 0.693147 \left(\Phi - \Phi_{o}\right) + \frac{1}{2} \left(\Phi - \Phi_{o}\right)^{2} \end{split} \tag{G7}$$

Equation (G7) gives values of  $\beta$  for values of  $(\Phi - \Phi_o)$  equal to or greater than  $60\pi/24$ . Values of the integral  $\beta$  are tabulated in table VII for a range of  $|(\Phi - \Phi_o)|$  between 0 and  $100\pi/24$  in increments of  $\pi/24$ . For negative values of  $(\Phi - \Phi_o)$ , the sign of  $\beta$  changes.

# APPENDIX H

### CHANNEL TURNING ANGLE

If the prescribed velocity distribution along one channel wall differs from the distribution along the other wall, then in general the channel deflects an amount  $\Delta\theta$ , which is the difference in flow direction far downstream and far upstream

of the region in which the prescribed velocity distribution varies. Thus,

$$\Delta \theta = \theta_d - \theta_u \tag{H1}$$

For large values of  $|(\Phi - \Phi_0)|$  such as occur far upstream and far downstream of the region in which the prescribed velocity varies along the channel walls

$$\cosh^2(\Phi-\Phi_o) >> \cos^2(\Psi-\Psi_o)$$

so that from equation (47)

$$G_0 = G_{\frac{\sigma}{2}} = -2[|(\Phi - \Phi_o)| - \log_o 2]$$
 (H2)

Far upstream  $\Phi_o < \Phi$  so that

$$|(\Phi - \Phi_o)| = (\Phi - \Phi_o)$$

and because V is harmonic

$$\int_{-\infty}^{\infty} \left[ \left( \frac{\partial \log_{\delta} V}{\partial \Phi} \right)_{\frac{\pi}{2}} - \left( \frac{\partial \log_{\delta} V}{\partial \Phi} \right)_{0} \right] d\Phi = 0$$

so that equation (H2) substituted into equation (46) gives

$$\theta_{u} = \frac{1}{\pi} \int_{-\infty}^{\infty} \Phi \left[ \left( \frac{\partial \log_{\epsilon} V}{\partial \Phi} \right)_{\frac{\pi}{2}} - \left( \frac{\partial \log_{\epsilon} V}{\partial \Phi} \right)_{0} \right] d\Phi$$
 (H3)

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Likewise, far downstream  $\Phi_o > \Phi$  so that

$$|(\Phi - \Phi_o)| = -(\Phi - \Phi_o)$$

and equation (H2) substituted into equation (46) gives

$$\theta_{d} = \frac{-1}{\pi} \int_{-\infty}^{\infty} \Phi \left[ \left( \frac{\partial \log_{\theta} V}{\partial \Phi} \right)_{\frac{\pi}{2}} - \left( \frac{\partial \log_{\theta} V}{\partial \Phi} \right)_{0} \right] d\Phi \qquad \text{(H4)}$$

From equations (H1), (H3), and (H4)

$$\Delta\theta = \frac{-2}{\pi} \int_{-\infty}^{\infty} \Phi \left[ \left( \frac{\partial \log_{\epsilon} V}{\partial \Phi} \right)_{\frac{\pi}{2}} - \left( \frac{\partial \log_{\epsilon} V}{\partial \Phi} \right)_{0} \right] d\Phi \quad (H5)$$

Equation (H5) determines the channel turning angle  $\Delta\theta$ .

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TABLE I—DISTRIBUTION OF VELOCITY Q AND FLOW DIRECTION  $\theta$  IN TRANSFORMED  $\varphi\psi$ -PLANE FOR EXAMPLE III (ELBOW WITH INCOMPRESSIBLE FLOW)

[Prescribed variation in Q with arc length s along channel walls plotted in fig. 2;  $Q_n=0.5, Q_d=1.0, \Delta\theta=89.36^\circ$ ]

V	(	)	0.1	25	0.2	250	0.3	75	0.4	500	0.6	325	0.7	750	0.1	B75	1.	000
P	Q	θ	Q	8	Q	θ	Q	θ	0	θ	Q	_ θ	0	θ	0	θ	0	. 0
-2 000 -1.875 -1.7625 -1.7625 -1.1626 -1.17625 -1.1626 -1.17626 -1	0. 5000 -500	0	0. 5000 .5000 .5000 .5000 .5001 .5001 .5001 .5001 .5001 .5002 .5003 .5003 .5005 .5016 .502	0	0. 5000 500	\$5555555555555555555555555555555555555	0. \$60 0. \$60	88555585585585585585585858585858585858	0. 5000 - 5001 - 5001 - 5001 - 5003 - 5003 - 5005 - 5003 - 5017 - 5038 - 5012 - 5038 - 5012 - 5038 - 5012 - 5038 - 5012 - 5038 - 5012 - 5038 - 5012 - 5038 - 5012 - 5038 -	0	0. 5000 5000 5000 5001 5002 5002 5003 5005 5003 5005 5003 5005 6005 600	00000000000000000000000000000000000000	0. 5000 . 5000 . 5000 . 5001 . 5002 . 5002 . 5005 . 5008 . 5012 . 5018 . 5028 . 5028 . 5028 . 5037 . 5037 . 5038 . 503	0010100283679144131346784473655146679849988654675767836444198866888888888888888888888888888888	0. 5000 . 5000 . 5000 . 5001 . 5001 . 5001 . 5001 . 5003 . 5004 . 5009 . 5014 . 5019 . 5023 . 5033 . 5014 . 5071 . 5023 . 5033 . 5034 . 5039 . 5033 . 5033 . 5033 . 5034 . 5037 . 5237 . 523	01000000000000000000000000000000000000	0. 5000 . 500	0 0101000000000000000000000000000000

# TABLE II—DISTRIBUTION OF PHYSICAL COORDINATES x AND y IN TRANSFORMED $\varphi\psi$ -PLANE FOR EXAMPLE III (ELBOW WITH INCOMPRESSIBLE FLOW)

[Prescribed variation in Q with arc length s along channel walls plotted in fig. 2;  $Q_u=0.5$ ,  $Q_d=1.0$ ,  $\Delta\theta=89.36^\circ$ ]

		)	0.1	125	0.5	250	0.3	775	0.4	500	0.6	325	0.7	750	0.8	375	1.	000
p	<i>x</i>	y	x	y	x	y	r	y	x	y	x	y	x	y	x	y	x	y
-2.000 -1.876 -1.750 -1.625 -1.377 -1.205 -1.207 -1	-3. 978 -3. 477 -3. 477 -3. 477 -1. 977 -1. 977 -1. 17		-3.7288	-0.748748748748748748748747747747747747747747746748748748749	-3.97882.27882.	-0.488 -1.488 -1.488 -1.488 -1.497 -1.496 -1.497 -1.496 -1.497 -1.496 -1.497 -1	-3.74288287288748928247293352448283335534443555355555555555555555	-0.2488 -0.248	-3.978 -3.728 -3	88888888888888888888888888888888888888	-3.728 -3.728	0. 2522 2522 2522 2522 2523 2523 2524 2525 2525	-3. 978 -3. 72	0.502 502 502 502 502 501 501 501 501 501 501 501 501	-3. 978 -3. 728 -3. 728 -3. 728 -3. 728 -3. 728 -3. 728 -3. 728 -3. 728 -3. 728 -3. 728 -3. 728 -1. 978 -1. 978 -1. 979 -7. 730 -1. 233 -1. 979 -7. 481 -1. 229 -7. 481 -1. 229 -7. 481 -1. 233 -1. 128 -1. 12	0. 762 . 762 . 762 . 762 . 762 . 762 . 762 . 761 . 750 . 749 . 746 . 747 . 747 . 748 . 747 . 748 . 747 . 748 . 748	-3. 978 -3. 727 -3. 727 -3. 727 -3. 227 -2. 277 -1. 977 -1. 277 -1. 977 -1. 27	1.002 1.002 1.002 1.002 1.002 1.002 1.002 1.002 1.002 1.002 1.001

# TABLE III—DISTRIBUTION OF VELOCITY q AND FLOW DIRECTION $\theta$ IN TRANSFORMED $\varphi*\psi*$ -PLANE FOR EXAMPLE IV (ELBOW WITH LINEARIZED COMPRESSIBLE FLOW)

[Prescribed variation in Q with arc length s along channel walls plotted in fig. 2;  $Q_s = 0.5$ ,  $Q_d = 1.0$ ,  $q_d = 0.80176$ ,  $\Delta \psi^* = 0.73782$ ,  $\Delta \theta = 104.07^\circ$ ]

V.	(	0		36		1/8	3	4	3	ś	5	6	1.	.0
φ <sup>*</sup> ΔV	q	θ	q	θ	q	θ	q	θ	q	0	q	θ	q	θ
11/6 -10	0. 4609 4072 4423 4489 4750 5515 5532 6602 7293 7793 7755 785	0 01 02 03 05 05 05 05 05 05 05 05 05 05 05 05 05	0. 4009 . 4009 . 4009 . 4009 . 4010 . 4011 . 4011 . 4011 . 4011 . 4012 . 4015 . 4018 . 4018 . 4019 . 4041 . 4070 . 4141 . 4654 . 4882 . 5118 . 5578 . 5578 . 5578 . 5578 . 5783 . 5783 . 5783 . 7894 . 6829 . 6924 . 6824 . 6824 . 6824 . 6824 . 6824 . 7045 . 7011 . 7081 . 7785 . 7853 . 7785 . 7853 . 7785 . 7853 . 7785 . 7859 . 7852 . 7853 . 7785 . 7853 . 7855 . 7850 . 7851 . 7785 . 7852 . 7853 . 7785 . 7853 . 7855 . 7850 . 7851 . 7785 . 7850 . 7851 . 7786 . 7813 . 7786 . 7813 . 7786 . 7813 . 7786 . 7813 . 7786 . 7813 . 7786 . 7813 . 7786 . 7813 . 7786 . 7813 . 7786 . 7813 . 7786 . 7813 . 7786 . 7813 . 7786 . 7813 . 7850 . 7801 . 8017 . 8017 . 8017 . 8017 . 8017 . 8017 . 8017	0 01 002 003 004 007 004 007 005 004 007 005 005 004 007 005 004 007 005 005 004 007 005 005 005 005 005 005 005 005 005	0. 4009 .4009 .4010 .4011 .4012 .4015 .4015 .4019 .4025 .4037 .4057 .4057 .4058 .4155 .4251 .4377 .4526 .4659 .4857 .5034 .5186 .5340 .5482 .5613 .5732 .5831 .6013 .6013 .6014 .6146 .6202 .6227 .6315 .6471 .6573 .6586 .6471 .7077 .7321 .7321 .7322 .7523 .7522 .7523 .7523 .7523 .7523 .7523 .7523 .7523 .7524 .7523 .7524 .7525 .7526 .7527 .7527 .7528 .7529 .7520 .7531	0 .00 .00 .00 .00 .00 .00 .00 .00 .00 .	0. 4009 4009 4009 4010 4010 4011 4013 4015 4020 4027 4039 4059 4059 4059 4059 4059 4059 4139 4207 4295 4396 4621 4734 4844 4947 5043 5183 5210 5221 5231 5231 5231 5231 5231 5231 5231	0 .000 .000 .000 .000 .000 .000 .000 .	0. 4009 4009 4000 40010 40010 40011 40012 40014 40018 40024 4003 4003 4008 40071 4104 4148 4202 4203 4203 4403 4403 4403 4403 4403	0	0. 4009 4009 4009 4010 4010 4011 4011 4011	0	0. 4009 4009 4009 4009 4009 4009 4009 4009	0

TABLE IV—DISTRIBUTION OF PHYSICAL COORDINATES x AND y IN TRANSFORMED  $\varphi^*\psi^*$ -PLANE FOR EXAMPLE IV (ELBOW WITH LINERARIZED COMPRESSIBLE FLOW)

[Prescribed variation in Q with arc length s along channel walls plotted in fig. 2;  $Q_a = 0.5$ ,  $Q_d = 1.0$ ,  $g_d = 0.80176$ ,  $\Delta \psi^* = 0.73782$ ,  $\Delta \theta = 104.07^\circ$ ]

V.		0	,	6	,	ś	34	<u> </u>	3:	ś	5	6	1	.0
$\frac{\varphi^{\bullet}}{\Delta V^{\bullet}}$	z	y	x	y	x	ij	x	Ŋ	x	y	x	y	x	y ·
-11/6 -10/8 -10/8 -10/8 -10/8 -9/8 -9/8 -9/8 -5/8 -4/8 -2/8 -2/8 -2/8 3/6 5/8 5/8 6/8 -11/8 11/8 11/8 11/8 11/8 11/8 11/8 1	-2. 466 -2. 241 -2. 241 -2. 241 -2. 166 -1. 791 -1. 566 -1. 341 -1. 116 891 -2. 468 -2. 421 -2. 168 -3. 450	-0.769 -1.769 -1.769 -1.769 -1.769 -1.769 -1.769 -1.769 -1.769 -1.769 -1.769 -1.769 -1.769 -1.769 -1.769 -1.769 -1.769 -1.769 -1.141 -1.1619 -1.1318 -1.1614 -1.1619 -1.1318 -1.1614 -1.1619 -1.1318 -1.1614 -1.1619 -1.1318 -1.1614 -1.1619 -	-2.2416 -2.2416 -1.7911 -1.5641 -1.5641 -1.116 -1.116 -1.1	-0.512	-2 466 -2 2416 -1. 2616 -1. 568 -1. 341 -1. 117 -1. 668 -1. 341 -1. 117 -1. 668 -1. 341 -1. 117 -1. 668 -1. 341 -1. 117 -1. 668 -1. 341 -1. 117 -1. 668 -1. 341 -1. 117 -1. 668 -1. 117 -1. 11	-0. 256 -1. 256 -1. 256 -1. 256 -1. 256 -1. 256 -1. 256 -1. 256 -1. 256 -1. 256 -1. 256 -1. 256 -1. 256 -1. 256 -1. 256 -1. 256 -1. 256 -1. 256 -1. 257 -1. 250 -1. 251 -1. 250 -1. 251 -1. 250 -1. 251 -1. 250 -1. 251 -1. 250 -1. 251 -1. 250 -1. 251 -1. 250 -1. 251 -1. 250 -1. 251 -1. 250 -1. 251 -1. 250 -1. 251 -1. 250 -1. 251 -1. 250 -1. 251 -1. 250 -1. 251 -1. 250 -1. 251 -1. 250 -1. 251 -1. 250 -1. 25	-2 486 -2 2416 -1 1.566 -1 1.566 -1 1.177 -3 688 -1 444 -3 000 -3 438 -3 453 -3 1254 -1 1.254 -1 1.254	0.001 .001 .001 .001 .001 .001 .001 .00	-2 468 -2 2411 -2 016 -1 566 -1 341 -1 117 - 868 -1 444 - 200 - 241 - 870 - 1 079 - 1 485 - 1 485 - 1 485 - 1 485 - 1 568 - 1 3 570 - 1 568 - 1 3 570 - 1 568 - 1 3 570 - 1 568 - 1 3 570 - 1 570 - 1 587	0. 257 257 257 257 257 257 257 257 257 257	-2 486 -2 241 -2 016 -1 586 -1 341 -1 116 - 867 - 443 - 005 - 228 - 449 - 670 - 318 - 1 104 - 1 118 -	0. 513 . 513 . 513 . 513 . 513 . 513 . 513 . 513 . 513 . 513 . 513 . 513 . 513 . 513 . 513 . 513 . 513 . 513 . 513 . 514 . 510 . 507 . 503 . 496 . 486 . 486 . 487 . 462 . 482 . 221 . 050 . 173 . 389 . 344 . 050 . 173 . 344 . 183 . 142 . 1898 . 1 680 . 1 182 . 1 680 . 1 888 . 2 027 . 2 189 . 1 680 . 1	-2.466 -2.241 -2.016 -1.566 -1.341 -1.116 -1.891 -1.416 -1.891 -2.489 -2.441 -2.16 -2.216 -3.441 -3.216 -3.441 -3.216 -3.441 -3.216 -3.441 -3.216 -3.441 -3.216 -3.441 -3.216 -3.441 -3.	0.770 .770 .770 .770 .770 .770 .770 .769 .769 .769 .769 .769 .768 .767 .768 .768 .767 .768 .768 .767 .768 .768

TABLE V—DISTRIBUTION OF VELOCITY q AND FLOW DIRECTION  $\theta$  IN TRANSFORMED  $\varphi\psi$ -PLANE FOR EXAMPLE V (ELBOW WITH COMPRESSIBLE FLOW  $(\gamma=1.4)$ )

[Prescribed variation in Q with arc length z along channel walls plotted in fig. 2;  $Q_a=0.5$ ,  $Q_d=0.79927$ ,  $\Delta \psi=0.71054$ ,  $\Delta \theta=105.31^\circ$ ]

$\frac{\psi}{\Delta \psi}$		0		<del>,</del>		<b>1</b> /4	!	4		16		)6	1	.0
<sup>φ</sup> / <sub>ΔΨ</sub>	q	в	q	θ	q	θ	q	•	q	θ	q	θ	q	0
-12/6 -11/6 -11/6 -11/6 -11/6 -10/6	0. 3996 3996 3996 3996 3996 3996 3996 3996	0 .001 .003 .005 .005 .005 .005 .005 .005 .005	0. 3996	0 .00 .01 .02 .00 .00 .00 .00 .00 .00 .00 .00 .00	0. 3996 3997 3997 3997 3997 3998 3999 4000 4002 4006 4014 4023 4047 4086 4182 4225 4389 4547 4719 4895 5099 5236 5333 5538 5669 5538 5538 5689 6578 6682 6884 6816 6852 77219 7845 77519 77519 77856 77519 77856 77959 77856 77959 77857 77857 77857 77857 77857 77857 77857 77858 77850	0 .000 .001 .012 .034	0. 3996 3997 3997 3997 3997 3997 3999 4000 4003 4003 4008 4015 4028 4019 4052 4134 4207 4300 4408 4524 4613 4762 4875 4881 5078 5166 5245 5314 5375 55122 5573 5522 5673 55720 6145 6516 67796 7789 7789 7789 7789 7789 7789	0 000000000000000000000000000000000000	0. 3996 3997 3997 3997 3997 3998 4000 4002 4006 4002 4008 4002 4008 4009 4009 4144 4228 428 4340 4413 4413 4413 4413 4413 4413 4413	0 .000   -0.	0. 3996 3997 3997 3997 3997 3997 3997 3997	0 .001 010 020 010 110 010 110 110 110 110	0. 3996 3996 3996 3996 3996 3996 3996 3996	0 .001

# TABLE VI—DISTRIBUTION OF PHYSICAL COORDINATES x AND y IN TRANSFORMED $\varphi\psi$ -PLANE FOR EXAMPLE V (ELBOW WITH COMPRESSIBLE FLOW $(\gamma=1.4)$ )

[Prescribed variation in Q with are length s along channel walls plotted in fig. 2;  $Q_u=0.5, Q_d=1.0, g_d=0.79927, \Delta \psi=0.71054, \Delta \theta=105.31^\circ$ ]

Ī	<u>ψ</u> Δψ	(	0	!	16	!	· ś	3	4	3	ś	5	6	1.	.0
	$\frac{\varphi}{\Delta \psi}$	x	y	_ x	v	x	y	<b></b>	y	x	y	x	y	x	y
•	-12/6 -11/6 -11/6 -11/6 -11/6 -19/6 -8/6 -8/6 -7/6 -6/6 -7/6 -4/6 -1/6 -1/6 -1/6 -1/6 -1/6 -1/6 -1/6 -1	-2.832 -2.595 -2.1592 -1.885 -1.648 -1.4174 -1.937 -1.464 -1.247 -1.937 -1.424 -1.531 -1.867 -1.424 -1.531 -1.867 -1.124 -1.531 -1.867 -1.124 -1.531 -1.867 -1.124 -1.531 -1.867 -1.124 -1.531 -1.867 -1.124 -1.531 -1.867 -1.124 -1.531 -1.867 -1.125 -1.867 -1.124 -1.531 -1.867 -1.125 -1.867 -1.867 -1.125 -1.867	-0.770 -1.780 -1	-2.832 -2.5358 -2.5358 -2.5358 -2.5358 -2.1222 -1.648 -1.1775 -1.648 -1.1775 -1.648 -1.1775 -1.466 -1.1775 -1.1	-0.513 -1	-2.832 -2.5358 -2.1232 -1.8856 -2.1232 -1.8856 -1.6431 -1.1776 -1.939 -1.4776 -1.939 -1.4776 -1.823 -1.823 -1.823 -1.826 -1.823 -1.826 -1.823 -1.826 -1.826 -1.826 -1.827 -1.	-0. 256 -1. 256 -1. 256 -1. 256 -1. 256 -1. 256 -1. 256 -1. 256 -1. 256 -1. 256 -1. 256 -1. 257 -1. 257 -1. 258 -1. 258 -1. 258 -1. 258 -1. 259 -1. 25	-2 832 -2 595 -2 123 -1 648 -1 175 -1 939 -1 467 -2 233 -2 122 -1 885 -1 175 -2 233 -3 200 -3 248 -3 200 -3 248 -3 248 -4 248	0.001 .001 .001 .001 .001 .001 .001 .00	-2. 832 -2. 595 -2. 12. 595 -2. 12. 595 -2. 12. 595 -2. 12. 595 -2. 12. 595 -2. 12. 595 -1. 648 -1. 411 -1. 938 -7. 702 -2. 467 -2. 234 -690 -1. 132 -2. 507 -2. 571 -2. 572 -2. 571 -2. 572 -2. 573 -	0. 258	-2.832 -2.595 -2.1022 -1.835 -2.122 -1.835 -1.1411 -1.938 -7.022 -1.855 -2.005 -2.403 -2.403 -2.403 -2.239 -2.403 -2.239	0. 514 . 514 . 514 . 514 . 514 . 514 . 514 . 514 . 514 . 513 . 513 . 513 . 512 . 510 . 507 . 502 . 483 . 483 . 411 . 618 . 443 . 411 . 618 . 617 . 762	-2.832 -2.595 -2.122 -1.835 -2.122 -1.848 -1.1411 -1.937 -701 -247 -701 -2484 -227 -1.859 -1.192 -1.484 -227 -2.953 -2.336 -2.1559 -2.336 -2.577 -2.953 -3.308 -3.501 -3.308 -3.3	0. 771 . 770 . 769 . 763 . 763 . 763 . 763 . 763 . 763 . 763 . 763 . 763 . 763 . 763 . 763 . 763 . 763 . 763 . 763 . 763 . 769 . 737 . 719 . 693 . 693 . 693 . 693 . 693 . 693 . 693 . 187 . 955 . 197 . 905 . 197 . 196 . 2 287 . 196 . 2 287 . 3 150 . 3 274 . 1 91 . 2 287 . 3 515 . 3 748 . 2 287 . 3 748 . 2 287 . 3 748 . 2 287 . 3 748 . 2 287 . 3 748 . 3 892 . 3 748 . 3 892 . 3 748 . 3 892 . 3 977 . 4 931 . 4 191 . 4 191 . 5 488 . 4 191 . 4 191 . 5 488 . 4 191 . 4 191 . 5 488 . 4 191 . 5 488 . 4 191 . 5 488 . 4 191 . 5 488 . 4 191 . 5 488 . 4 191 . 5 488 . 4 191 . 5 488 . 4 191 . 5 488 . 4 191 . 5 488

TABLE VII—TABULATED VALUES OF THE INTEGRALS  $\alpha$  AND  $\beta$  FOR A RANGE OF  $|(\Phi-\Phi_o)|$  [Computational methods given in appendix G]

	m	Δ1	[⇔Δα	a(ı)	ΔΙ•	= Δβ
[(Φ—Φ•)	α <sup>(1)</sup>	Δια (ΔΦ=π/24)	$\Delta_{1}\alpha$ $(\Delta \Phi = 2\pi/24)$	βω	Διβ (ΔΦ= π/24)	$\Delta_{2}\beta$ $(\Delta \Phi = 2\pi/24)$
0	0			0		
1(\pi/24)	. 000373	0.000373	0.002970	396937	-0.396937	-0.611680
· 2(\pi/24)	. 002970	.002597		<b></b> 611660	214723	
3( <del>x/24</del> )	.009942	.006972	. 020331	756406	144748	242791
4(\pi/24)	. 023301	. 013359		854451	098045	
5(x/24)	. 044875	.021574	. 052976	916486	062035	094079
6( <del>π</del> /24)	. 076277	.031402		948530	032044	
7( <del>π</del> /24)	. 118897	. 042620	. 097632	954346	005816	.012092
8( <del>x</del> /24)	. 173909	. 055012	ļ	936438	.017908	
9(x/24)	. 242283	. 068374	.150903	896542	. 039896	.100542
10(x/24)	. 824812	. 082529		835896	. 060646	
11(#/24)	. 422136	. 097324	. 209951	755399	. 080497	. 180181
12(#/24)	. 534763	. 112627		655715	. 099684	
13(#/24)	. 663098	. 128335	. 272697	537338	. 118377	. 255075
14(π/24)	.807460	. 144362		400640	. 136698	
15(#/34)	.968096	. 160636	.837741	245901	. 154739	. 327305
16(1/24)	1. 145201	. 177105		073335	. 172566	102.000
	1.338926	. 193725	404109		. 190232	. 398006
17(#/24)		. 210463	. 404188	. 116897	. 207774	.00000
18(#/24)	1. 549389	. 227290	477 4790	.324671	. 225221	407017
19(π/24)	1.776679	. 244188	471478	. 549892	. 242596	. 467817
20(π/24)	2.020867	. 261141		. 792488	. 259915	F27100
21(x/24)	2. 282008	. 278135	. 539276	1.052403	. 277191	. 537106
22(π/24)	2. 560143	. 295161		1.329594	. 294435	******
23(#/24)	2.855304	. 312212	.607373	1. 624029	.311654	. 606089
24(π/24)	3. 167516	. 329283		1.935683	.328853	
25(=/24)	3. 496799	. 346369	675652	2. 264536	. 346037	. 674890
26(π/24)	3.843168	. 363465	<u> </u>	2.610573	.363210	
27(±/24)	4. 206633	. 380570	.744035	2.973783	. 380375	.743585
28(#/24)	4. 587203	397682		3.354158	.397531	
29(±/24)	4. 984885	. 414800	.812482	3. 751689	. 414684	.812215
30( <del>*/24</del> )	5. 399685	431922	· · · · · · · · · · · · · · · · · · ·	4. 166373	.431832	
31(#/24)	5.831607	. 449045	.880967	4. 598205	.448976	.880808
32( <del>x</del> /24)	6. 280652	.466173	<del> </del>	5. 047181	. 466120	
33( <del>x</del> /24)	6.746825	. 483301	. 949474	5. 513301	. 483260	. 949380
34(*/24)	7. 230126	.500431	<del></del>	5. 996561	.500400	
35( <del>x</del> /24)	7. 730557	. 517562	1.017993	6. 496961	. 517538	1.017938
36(x/24)	8. 248119	.534694		7.014499	. 534676	
37(=/24)	8. 782813	. 551827	1. 086521	7. 549175	. 551812	1.086488
38(#/24)	9. 334640	. 563960	<del> </del>	8. 100987	. 568949	· · · · · ·
39(=/24)	9. 903600		- 1. 155053	8. 669936	: 586085	1.155034
40(x/24)	10. 489693	. 586093	<del> </del>	9. 256021		
41(#/24)	11.092920	. 603227	1. 223588	9.859241	603220	1. 223576
42(1/24)	11. 713281	. 620361		10. 479597	. 620356	
43(=/24)	12. 350777	. 637496	1. 292125	11. 117089	.637492	1. 292118
44(±/24)	13. 005406	. 654629		11. 771715	- 654626	<u> </u>
45(±/24)	13. 677170	. 671764	1.360662	12.443477	. 671762	1.860658
46(π/24)	14. 386068	.688898	<u> </u>	18. 132373	. 688896	<u>·</u>
47(=/24)	15.072101	. 706033	1. 429200	18.838405	.706032	1. 429198
		. 723167	1	14. 561571	. 723166	ļ
48(=/24)	15.795268			14.001011	.740302	

<sup>(1)</sup> For negative values of  $(\Phi - \Phi_{\bullet})$  the signs of  $\alpha$  and  $\beta$  change, but the signs of  $\Delta \alpha$  and  $\Delta \beta$  remain unchanged.

TABLE VII—TABULATED VALUES OF THE INTEGRALS  $\alpha$  AND  $\beta$  FOR A RANGE OF  $|(\Phi-\Phi_o)|$ —Concluded. [Computation methods given in appendix G.]

		ΔΙ-	<b>-</b> Δα		ΔΙ=	- Δβ
[(Φ—Φ•)	α <sup>(1)</sup>	Δια	$\Delta_{2\alpha}$ $(\Delta \Phi = 2\pi/24)$	βω	Διβ	$\Delta_{1}\beta$ ( $\Delta\Phi = 2\pi/24$ )
50(x/24)	17. 293007	(ΔΦ=π/24)	(ΔΦ=2π/24)	16. 059309	(ΔΦ=π/24)	(ΔΦ=2 <del>x</del> /2 <del>1</del> )
51 ( <del>x</del> /24)	18, 067579	0.774572	1.566278	16, 833880	0.774571	1, 566276
52( <b>π</b> /24)	18, 859285	. 791708		17. 625585	. 791705	
53(=/24)	19. 668125	. 808840	1, 634816	18, 434426	. 808841	1.634816
54(±/24)	20, 494101	. 825976	1, 30,1010	19. 260401	. 825975	1.001010
55(x/24)	21, 337211	. 843110	1.703355	20. 103511	. 843110	1,703354
56(x/24)	22, 197456	. 860245	1.7000	20. 963755	. 860244	1.100001
57(±/24)	23, 074835	. 877379	1.771893	21.841135	. 877380	1.771894
58( <del>x</del> /24)	23.969349	. 894514	1.771000	22, 735649	. 8 <del>9</del> 4514	1.771001
59(#/24)	24. 880998	. 911649	1.840433	23. 647298	. 911649	1.840433
	25. 809782	. 928784	1.010100	·	. 928784	1.040403
60(x/24)		. 945912	1 000000	24, 576082	. 945912	* 000000
61 (#/24)	26, 755694	. 963056	1.908968	25. 521994	. 963056	1,908968
62( <del>x</del> /24)	27.718750	. 980190		26. 485050	. 980190	
63( <del>x</del> /24)	28. 698940	. 997317	1.977507	27. 465240	. 997317	1.977507
64(#/24)	29. 696257	1.014460		28, 462557	1.014460	
65( <del>#</del> /24)	30. 710717	1.031594	2.046044	29.477017	1.031594	2.046044
66( <del>1</del> /24)	31.742311	1.048722		30, 508611	1.048722	
67(±/24)	32. 791033	1.065863	2.114585	31. 557333	1.065863	2, 114585
68( <del>x</del> /24)	33, 856896	1.082999		32, 623196	1.082999	
69(x/24)	34. 939895	1.100134	2.183123	33. 706195	1.100134	2, 183123
70( <del>x</del> /24)	36. 040029	1.117260		34. 806329	1.117280	
71 (#/24)	37.157289	1.134403	2. 251663	35, 923589	1. 134403	2. 251663
72( <del>x</del> /24)	38. 291692	1.151538		37. 057992	1.151538	<u> </u>
73(x/24)	39. 443230	1.168663	2. 320201	38. 209530	1.168663	2. 320201
74(#/24)	40. 611893	1.185808		39, 378193	1.185808	
75( <del>x</del> /24)	41.797701	1. 202942	2, 388740	40. 564001	1, 202942	2. 388740
76(±/24)	43.000643	1. 220067	-	41.766943	1. 220067	
77( <del>x</del> /24)	44. 220710	1. 237212	2, 457279	42.987010	1. 237212	2.457279
78( <del>x</del> /24)	45. 457922	1. 254847		44. 224222	1, 254347	
79( <del>x</del> /24)	46. 712269	1. 271481	2. 525818	45. 478569	1. 271481	2. 525818
80(x/24)	47. 983750	1. 288606	<u> </u>	46. 750050	1. 288606	
81(#/24)	49. 272356	1.305751	2. 594357	48. 038656	1.305751	2. 594357
82( <del>#/24</del> )	50. 578107	1.322885		49. 344407	1, 322885	
83( <del>x</del> /24)	51.900992	1.340010	2, 662895	50. 687292	1.340010	2. 662895
84(\pi/24)	53, 241002	1.357156		52,007302	1.357156	<del></del>
85( <b>x/24</b> )	54. 598158	1. 374289	2, 731435	53. 364458	1.374289	2.731435
86(#/24)	55. 972447	1.391414		54. 738747	1.391414	
87( <del>π</del> /24)	57. 363861	1. 408560	2. 799974	56. 130161	1. 408560	2.799973
88( <del>x</del> /24)	58. 772421	1.425694	<del> </del>	57. 538720	1. 425694	
89(#/24)	60. 198115	1.442818	2.868512	58.964415	1.442818	2, 868513
90(=/24)	61.640933	1. 459964		60. 407233		ļ
91(#/24)	63. 100897		2, 937052	61. 867197	1.459964	2.937052
92(x/24)	. 64. 577995	1,477098	<u> </u>	63. 344295	1.477098	
93(π/24)	66, 072228	1. 494233	3.005590	64. 838528	1. 511857	8,005590
94(1/24)	67. 583585	1. 528503	<del> </del>	66. 349885	1. 528503	-
95( <del>x</del> /24)	69.112088	1. 545687	3. 074130	67. 878388	1. 545637	8.074130
96(π/24)	70. 657725	1. 540087	<del> </del>	69. 424025	1.562761	
97(x/24)	72, 220486	1. 579907	3.142663	70. 986786	1. 579907	3.142668
98(#/24)	73, 800393	1. 597042		72. 566693	1. 597042	<del> </del>
99(#/24)	75, 397435	1. 614164	- 3. 211206	74. 163785	1. 614164	3. 211208
100(π/24) (2)	77.011599	1.014104	<del> </del>	75. 777899	1.013104	<del> </del>

<sup>(1)</sup> For negative values of  $(\Phi - \Phi_o)$  the signs of  $\alpha$  and  $\beta$  change, but the signs of  $\Delta \alpha$  and  $\Delta \beta$  remain unchanged. (3) For values of  $|(\Phi - \Phi_o)| > 100(\pi/24)$  use equation (G2) for  $\alpha$  and equation (G7) for  $\beta$ .

# TABLE VIII—COMPARISON OF ELBOW DESIGNS OBTAINED FROM SOLUTIONS BY RELAXATION METHODS AND BY GREEN'S FUNCTION

[Linearized compressible flow; prescribed velocity distribution given in figs. 2 and 22.]

				Ψ=0 (In	ner wall)				Ī			Ψ=π/2 (0	outer wall)		•	
Φ	Q	q	Solut me	ion by rela thods (Par	xation t I)	Solution	by Green' (Part II)	s function	Q.	q	Solut. me	ion by rela thods (Par	xation t I)	Solution	by Green (Part II)	's function
			r	y	θ (deg)	x	y	θ (deg)		_	I	y	(deg)	x	y	(deg)
-22 (π/24) -28 (π/24) -28 (π/24) -18 (π/24) -18 (π/24) -116 (π/24) -12 (π/24) -12 (π/24) -10 (π/24) -12 (π/24) -14 (π/24) -2 (π/24) -2 (π/24) -12 (π/24) -12 (π/24) -12 (π/24) -12 (π/24) -13 (π/24) -14 (π/24) -15 (π/24) -16 (π/24) -16 (π/24) -16 (π/24) -16 (π/24) -17 (π/24) -	0.5000 .0000 .0000	0. 4009 4009 4009 4009 4009 4009 4009 4009	-2. 466 -2. 2416 -1. 7966 -1. 7966 -1. 1118 -1. 11891 -1. 11	-0. 769 769 769 769 769 769 768 768 768 768 768 768 766 767 766 767 767 776 772 772 772 772 772 772 772 781 822 821 821 821 821 821 821 822 821 822	0 010.023	-2.2466 -2.2416 -2.2416 -1.7566 -1.7566 -1.7566 -1.1118 -1.1181 -1.118	-0.769769769769769768768768768766763765763775771773724713724711727783827929 -1.066 -1.144 -1.516 -1.516 -1.516 -1.516 -1.727 -1.516 -1.620 -1.415 -1.516 -1.727 -1.837 -1.948 -2.2853 -3.633 -3.3633	0 00 00 00 00 00 00 00 00 00 00 00 00 0	0. 5000 500	0. 4009 4009 4009 4009 4009 4009 4009 4009	-2. 466 -2. 2416 -1. 7666 -1. 7666 -1. 1166 -1. 1166 -1. 11666 -1. 11666 -1. 11666 -1. 11666 -1. 11666 -1. 11666 -1. 11666 -1. 11666 -1. 116666	0.770 .770 .770 .770 .770 .770 .770 .77	0 01 - 0.02 03 03 05	-2. 466 -2. 2416 -1. 7916 -1. 7916 -1. 7916 -1. 341 -1. 1169 -1. 341 -1. 1169 -234 -468 -246 -246 -246 -246 -246 -246 -246 -246	0.770 .770 .770 .770 .770 .769 .768 .768 .765 .763 .763 .673 .673 .673 .673 .673 .673	0